

# Free Discontinuity Regression

**With an Application to the Economic Effects of Internet Shutdowns**

**David Van Dijcke**

**University of Michigan\Ipsos Public Affairs**

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Cornell University



joint with Florian Gunsilius (Emory)



# Introduction

- Discontinuous changes in regression surfaces can reveal fundamental insights into underlying problem structure
- Especially when both **location** and **size** of discontinuity are unknown
  - **Location**: treatment assignment mechanisms, structural breaks, change points...
  - **Size**: causal effects of treatment (under extra assumptions), magnitude of regime shift, etc.
- **This paper: statistical method for estimating regression surface together with discontinuities in any dimension**
  - Statistical reformulation of celebrated Mumford-Shah functional from computer vision
  - No pointwise smoothness assumptions on discontinuity set
  - *Segmentation*: balances function estimation, denoising, and thresholding
- Examples:
  - **Confidential assignment algorithms**: loan/financial aid disbursement (Argyle et al., 2020; Carneiro et al., 2019), school admission (Brunner et al., 2021), customer segmentation for marketing (Hartmann et al., 2011), bandit algorithms (Li et al., 2010)
  - **Behavioral discontinuities**: tax brackets ("fuzzy" thresholds) (Saez, 2010; Alvero and Xiao, 2023), racial segregation (Card et al., 2008), tipping points Hospital Stress Responses (Kuntz et al., 2015)
  - **Complex Systems/Tipping Points**: Climate Change (Scheffer et al., 2009), Financial Markets (Hansen, 2017)
  - **Geographic Discontinuities**: Broadcast Signal Penetration (Sonin and Wright, 2022; Kern and Hainmueller, 2009; Olken, 2009), Epidemic Spread (Ambrus et al., 2020)

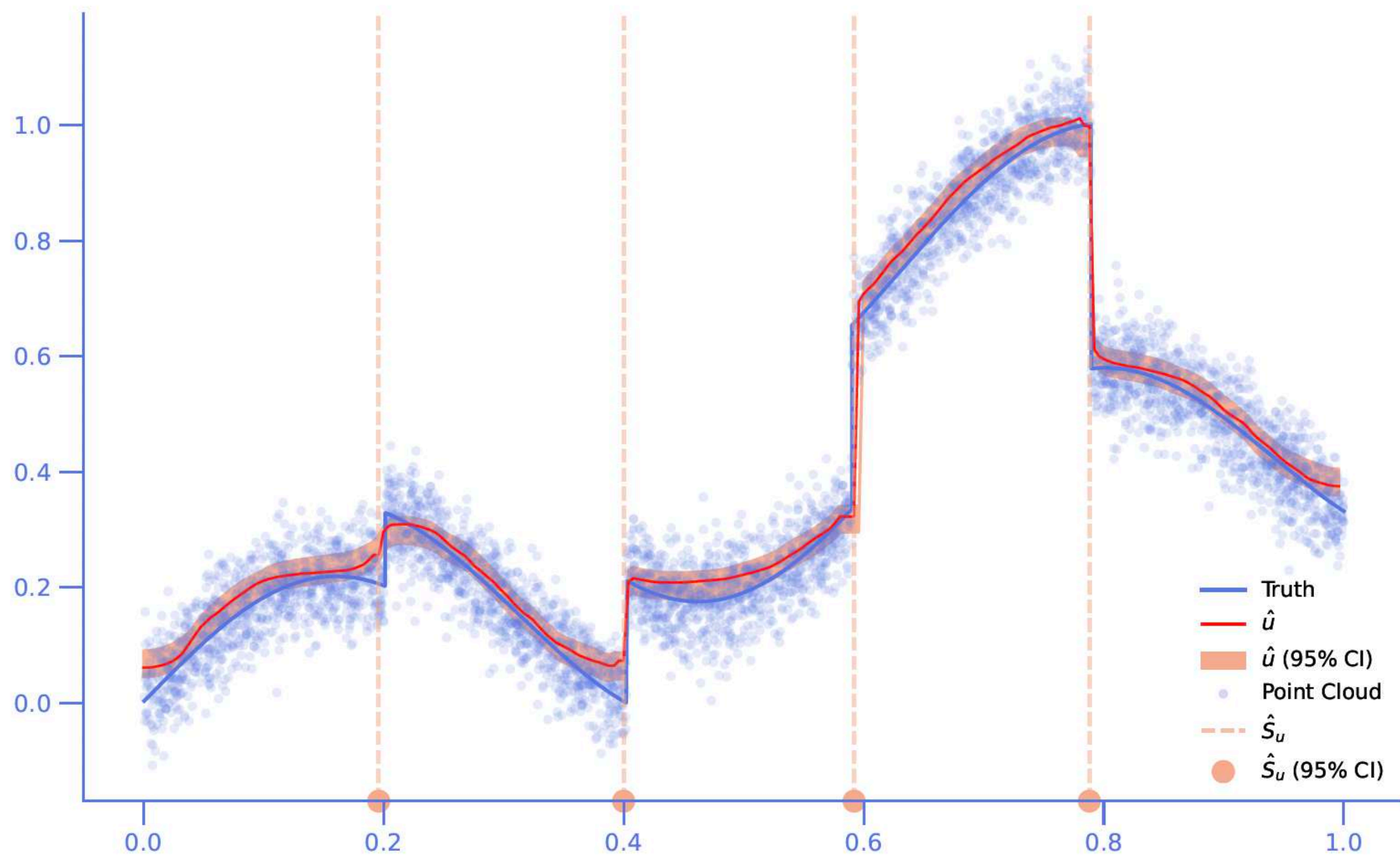
# Existing approaches

- **Change point detection:** Page (1954), Killick et al. (2012), Porter and Yu (2015), Donoho and Johnstone (1994), Harchaoui et al. (2008).
  - Focus on estimating discontinuity locations, less emphasis on estimating jump sizes.
- **Structural breaks:** Andrews (1993), Bai and Perron (2003), Delgado and Hidalgo (2000).
  - Time as a primary input variable — one-dimensional.
- **Extensions to multivariate domains** (Park, 2022; Herlands et al., 2018, 2019; Zhu et al., 2014; Madrid Padilla et al, 2022)
  - No statistical results, focus on discontinuity locations
  - Multivariate discontinuities in economics: Cheng (2023), Narita and Yata (2021), Abdulkadiroglu et al. (2022), Cattaneo and Titiunik (2022).
- **Regression surfaces with jumps:** Qiu and Yandell (1997), Korostelev and Tsybakov (1993), O'Sullivan and Qian (1994), Muller and Song (1994), Donoho (1999), Li and Ghosal (2017), Qiu (1998).
  - Multidimensional jump estimation under strong assumptions on discontinuity set.
- **Fused Lasso:** Tibshirani et al. (2005), Rinaldo (2009), Harchaoui and Lévy-Leduc (2010).
  - Piecewise constant functions on multivariate domains.

# Our contribution

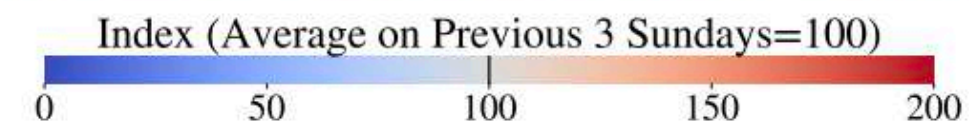
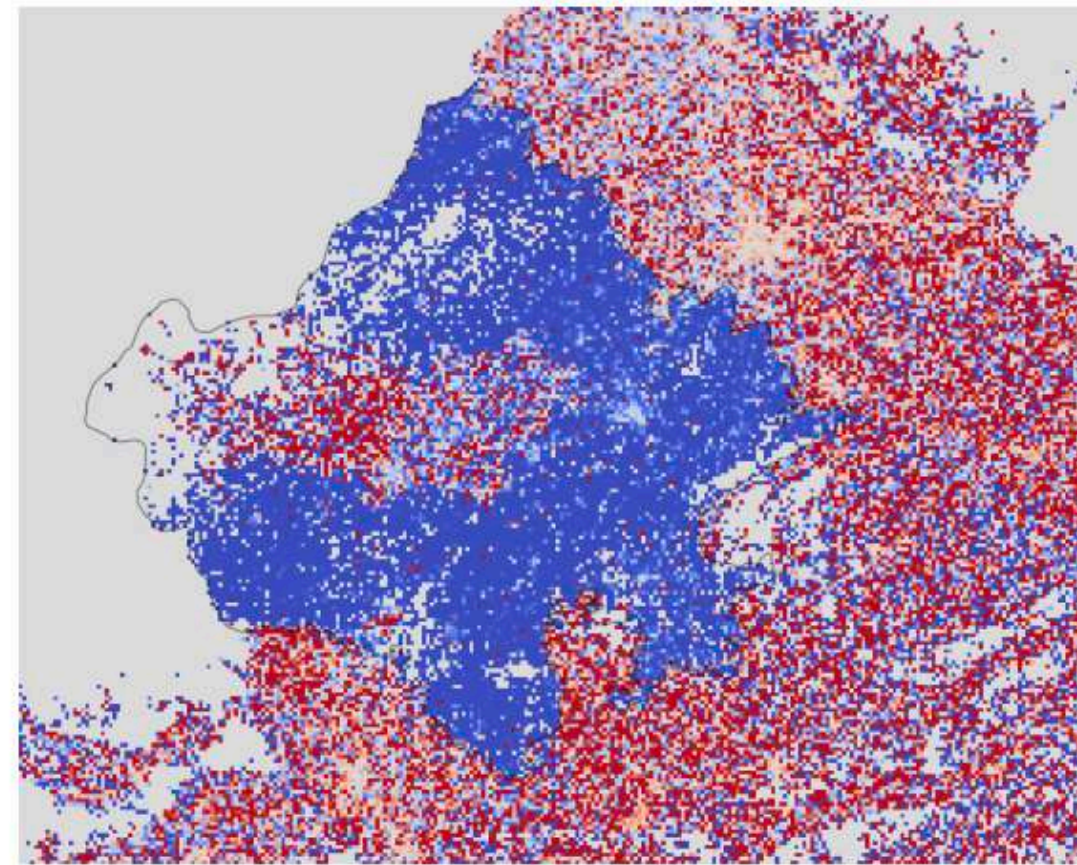
- **Statistical convergence** results for convex estimator
- **Jointly estimate** discontinuity locations and size with regression surface
- **Identification** results: identify true jump locations and sizes at limit
- For **general discontinuity** set in any dimension
- **Application** to internet shutdowns, implemented in PyTorch library

# Preview of Results

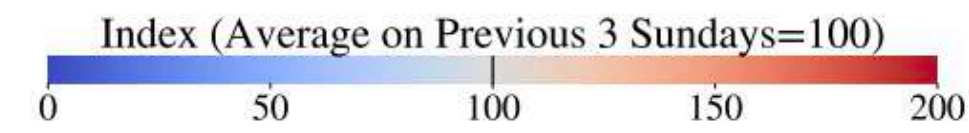
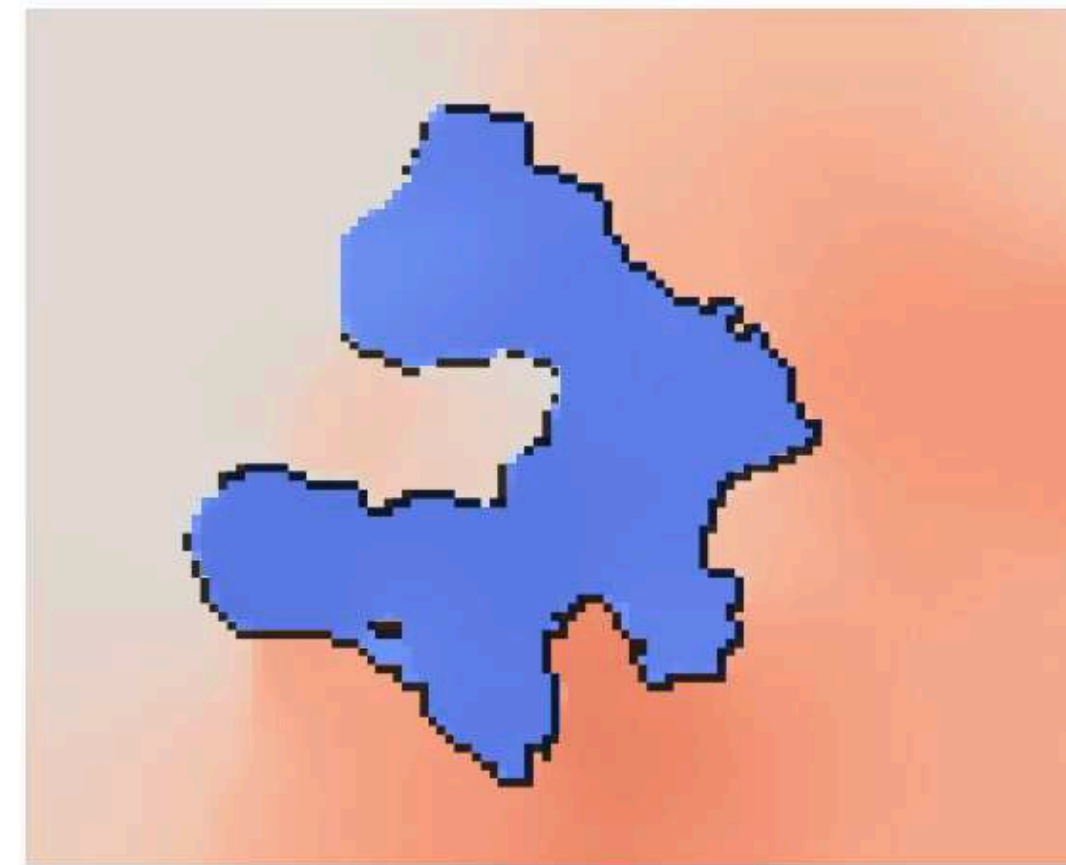


(a) 1D: Truth + Point Cloud +  $\hat{u}$  + Boundary

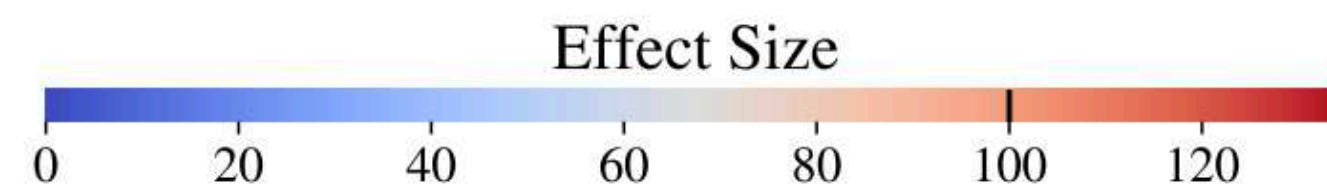
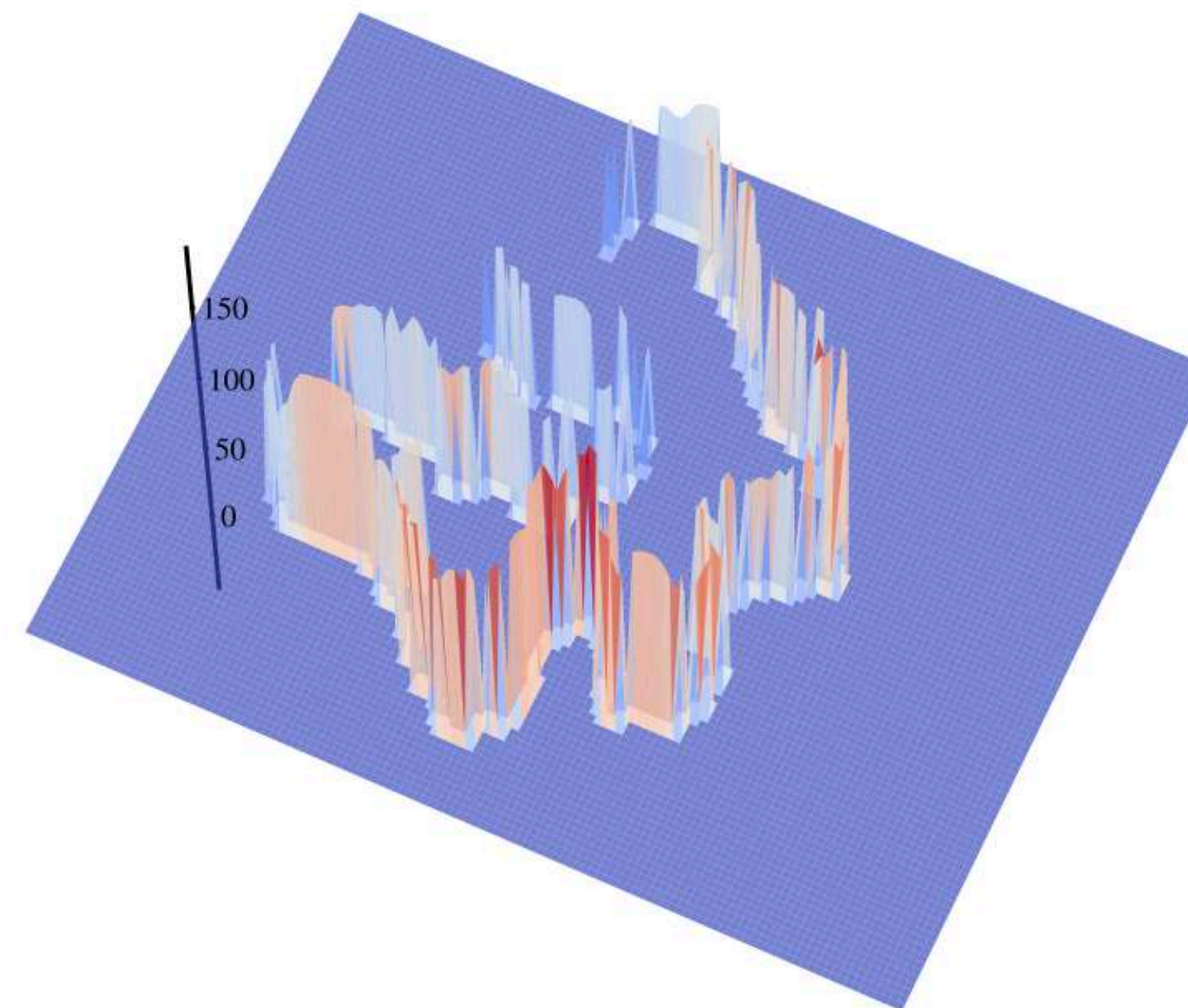
# Preview of Results



(a) Mobile: Raw Data



(b) Mobile:  $\hat{u}$  &  $S_u$



# Regression framework

- $i = 1, \dots, n$  units
- $X_i \in \mathbb{R}^d$  potentially multivariate regressor
- $Y_i \in \mathbb{R}$  outcome of interest (can be extended to  $\mathbb{R}^d$ )
- Regression model:

$$Y_i = f(X_i) + \varepsilon_i, \quad \mathbb{E}[\varepsilon_i | X_i] = 0, \quad \varepsilon_i \sim \text{i.i.d.}$$

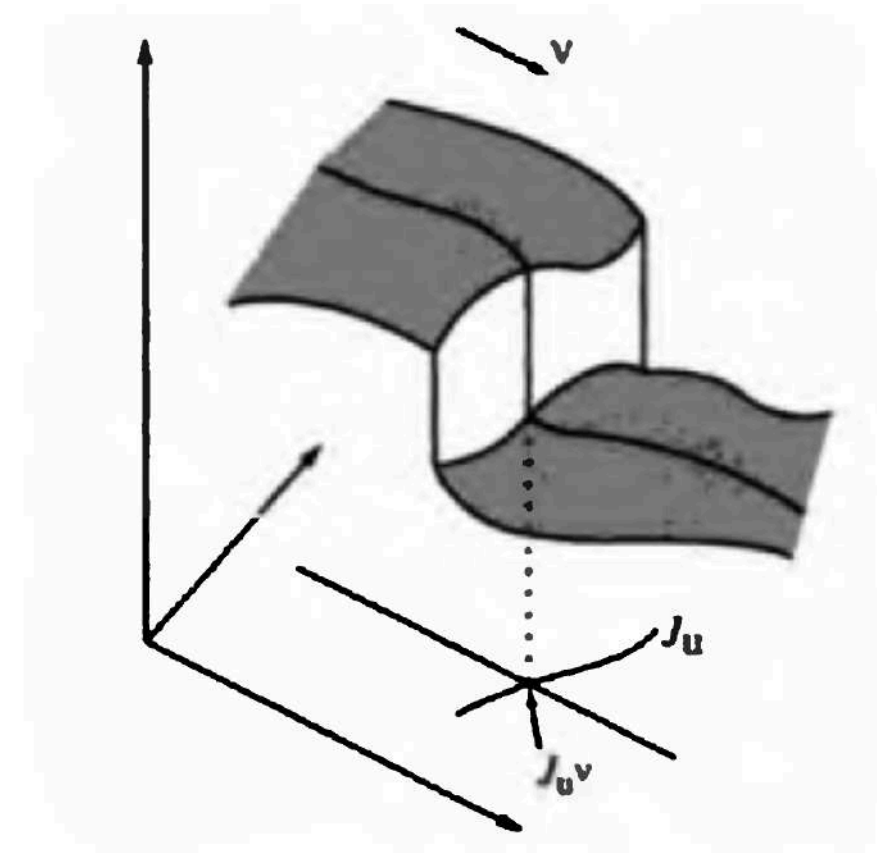
- **Goal:** estimate regression surface  $f(x)$  including location and jump sizes of discontinuity set  $S_f$

# Multivariate discontinuities

**Definition** Let  $u \in L^1(\mathcal{X})$ , we say that  $u$  is a **function of bounded variation** in  $\mathcal{X} \subset \mathbb{R}^d$  if the distributional derivative  $Du$  is representable by a finite Radon measure in  $\mathcal{X}$ , i.e. if

$$\int_{\mathcal{X}} u \operatorname{div} \varphi dx = - \sum_{i=1}^d \int_{\mathcal{X}} \varphi_i dD_i u \quad \forall \varphi_i \in C_c^1(\mathcal{X})$$

for some  $\mathbb{R}^n$ -valued Radon measure  $Du = (D_1 u, \dots, D_d u)$  in  $\mathcal{X}$ .

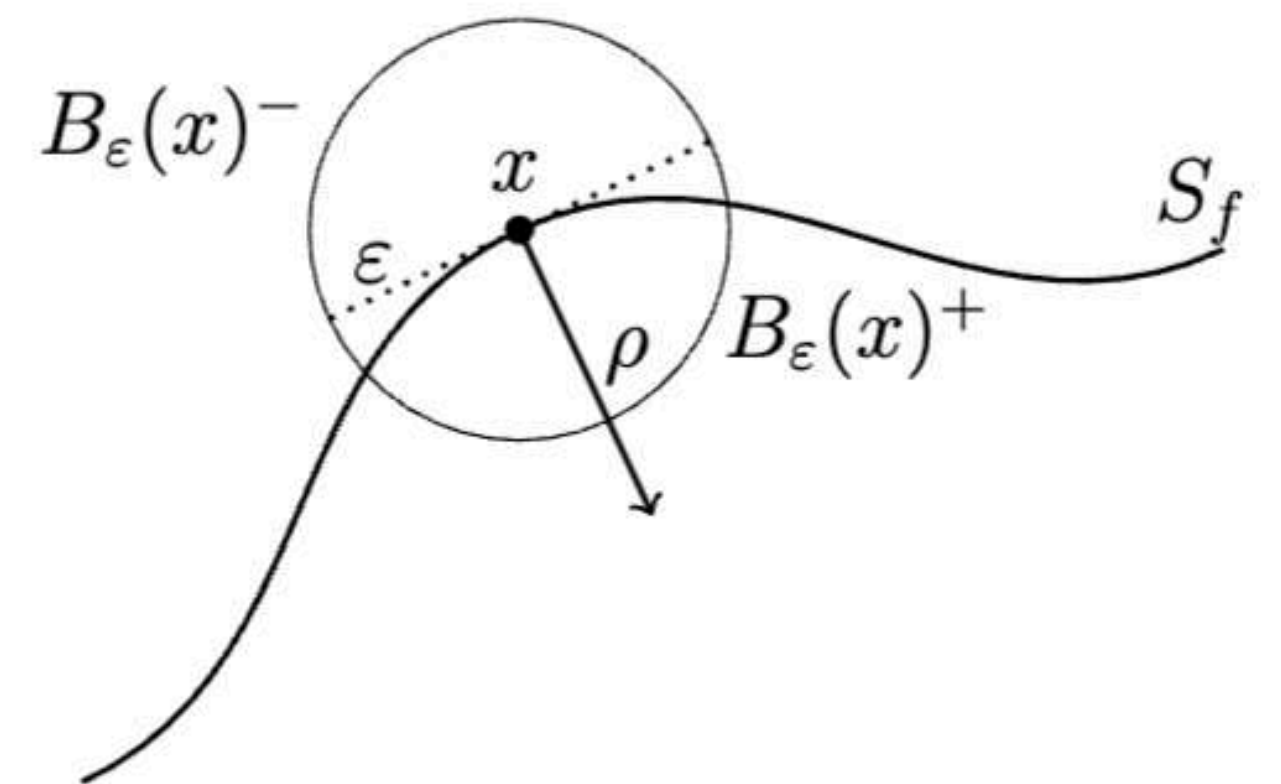


Ambrosio. Fusco. Pallara. 2000

**Definition** Let  $u \in L^1_{loc}(\mathcal{X})$ . Then  $x \in \mathcal{X}$  is an **approximate jump point** of  $u$  if there exists  $a \neq b \in \mathbb{R}$ ,  $\nu \in \mathbb{S}^{d-1}$  such that

$$\lim_{\varepsilon \downarrow 0} \int_{B_\varepsilon^+(x, \nu)} |u(y) - a| dy = 0. \quad \lim_{\varepsilon \downarrow 0} \int_{B_\varepsilon^-(x, \nu)} |u(y) - b| dy = 0.$$

$$\begin{cases} B_\varepsilon^+(x, \nu) := \{y \in B_\varepsilon(x) : \langle y - x, \nu \rangle > 0\} \\ B_\varepsilon^-(x, \nu) := \{y \in B_\varepsilon(x) : \langle y - x, \nu \rangle < 0\} \end{cases}$$



Then we denote the **set of jump points of function  $u$**  as  $S_u$



# Free Discontinuity Regression via the Mumford-Shah functional

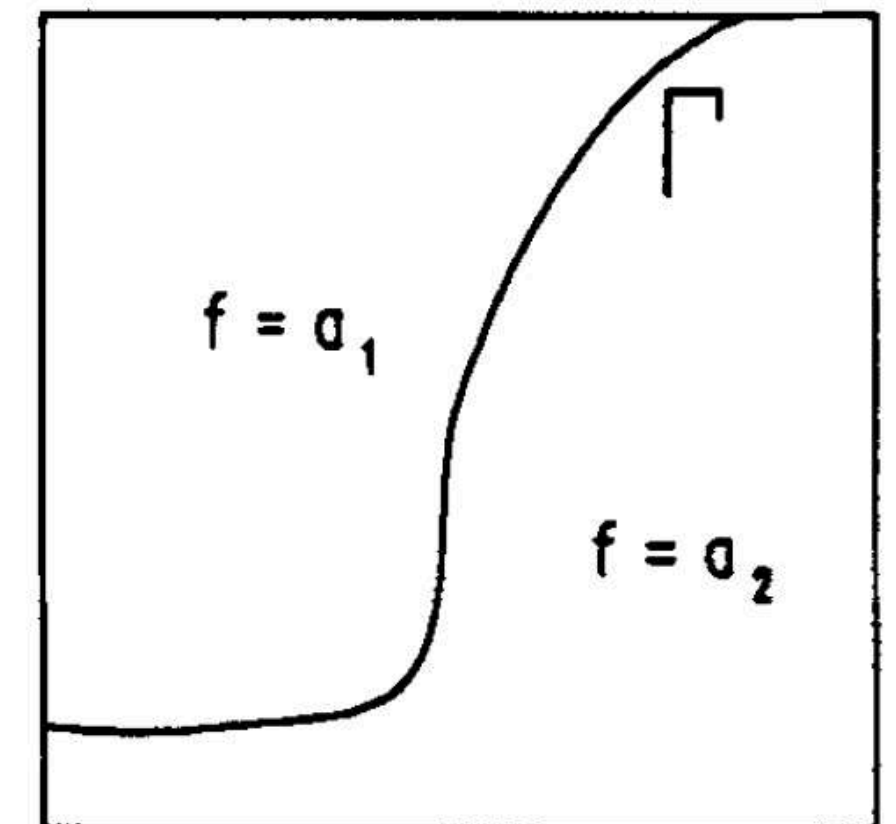
Our statistical version of the Mumford-Shah functional is defined as:

$$E(u) = \underbrace{\lambda \int_{\mathcal{X}} (f - u)^2 f_X(x) dx}_{\text{Regression}} + \underbrace{\int_{\mathcal{X} \setminus S_u} |\nabla u|^2 f_X(x) dx}_{\text{Roughness penalty away from discontinuity}} + \underbrace{\nu \mathcal{H}^{d-1}(S_u)}_{\text{Boundary regularity penalty}}$$

where  $\mathcal{X}$  is the support of  $u(x)$ ,  $f_X(x)$  is the density of  $X$ ,  $S_u$  is its discontinuity set, and  $\mathcal{H}^{d-1}$  is the Hausdorff measure in  $d-1$  dimensions.

Natural improvement of naive edge detection approaches. Benefits:

1. **one-step denoising + thresholding**
2. **imposes boundary regularity using global function information**
3. **explicitly estimates the discontinuity set**



# Convexifying the problem

The MS functional is not convex  $\implies$  local solutions and bad artifacts, **issue in particular for statistical inference!**

**Solution:** Convexification via the **calibration method** (Alberti, Bouchitté, dal Maso 2003; Pock et al 2009)

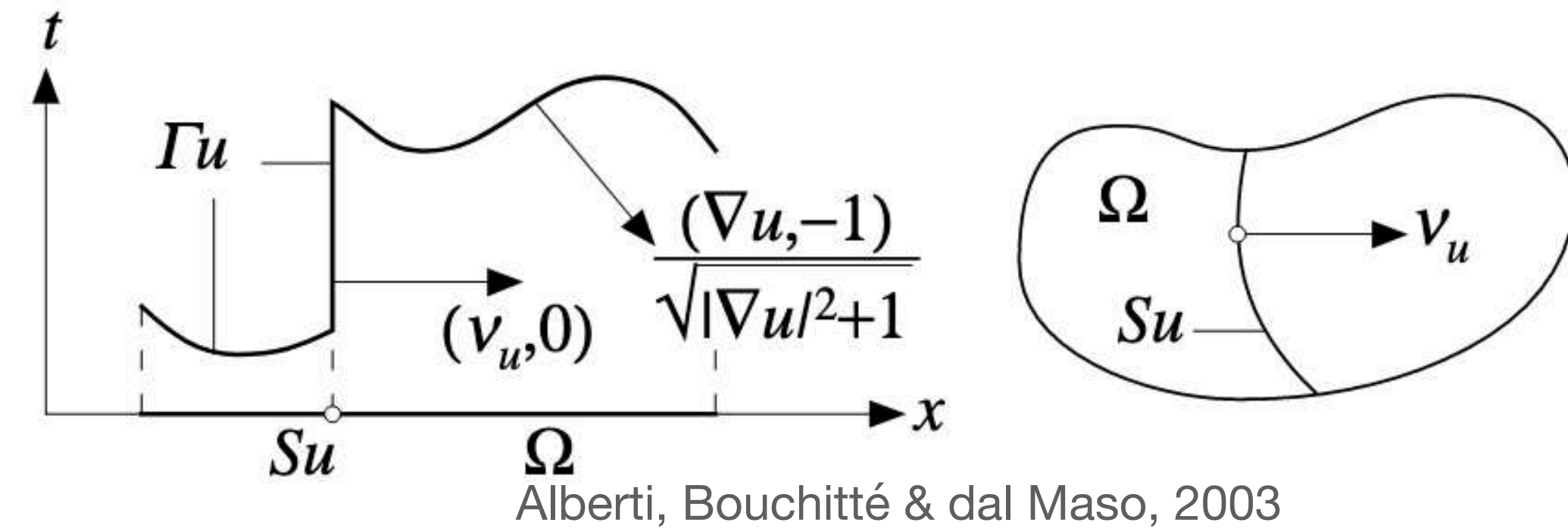
$$E(u) = \sup_{p \in K} \int_{\mathcal{X} \times \mathbb{R}} p \cdot D1_u \quad \text{with } 1_u := 1_{u(x) > t}(x, t)$$

$$K = \left\{ p \in C_0(\mathcal{X} \times \mathbb{R}, \mathbb{R}^{d+1}) : p^t(x, t) \geq \frac{|p^x(x, t)|^2}{4 f_X(x)} - \lambda f_X(x)(t - f(x))^2 \right.$$

$$\left. \text{and } \left| \int_{t_1}^{t_2} p^x(x, s) ds \right| \leq \nu \right\}$$

**Additional convexification:** replace  $1_u$  with  $v \in C$  where

$$C = \left\{ v \in SBV(\mathcal{X} \times \mathbb{R}) \mid v : \mathcal{X} \times \mathbb{R} \rightarrow [0, 1], \lim_{t \rightarrow -\infty} v(x, t) = 1, \lim_{t \rightarrow +\infty} v(x, t) = 0 \right\}$$

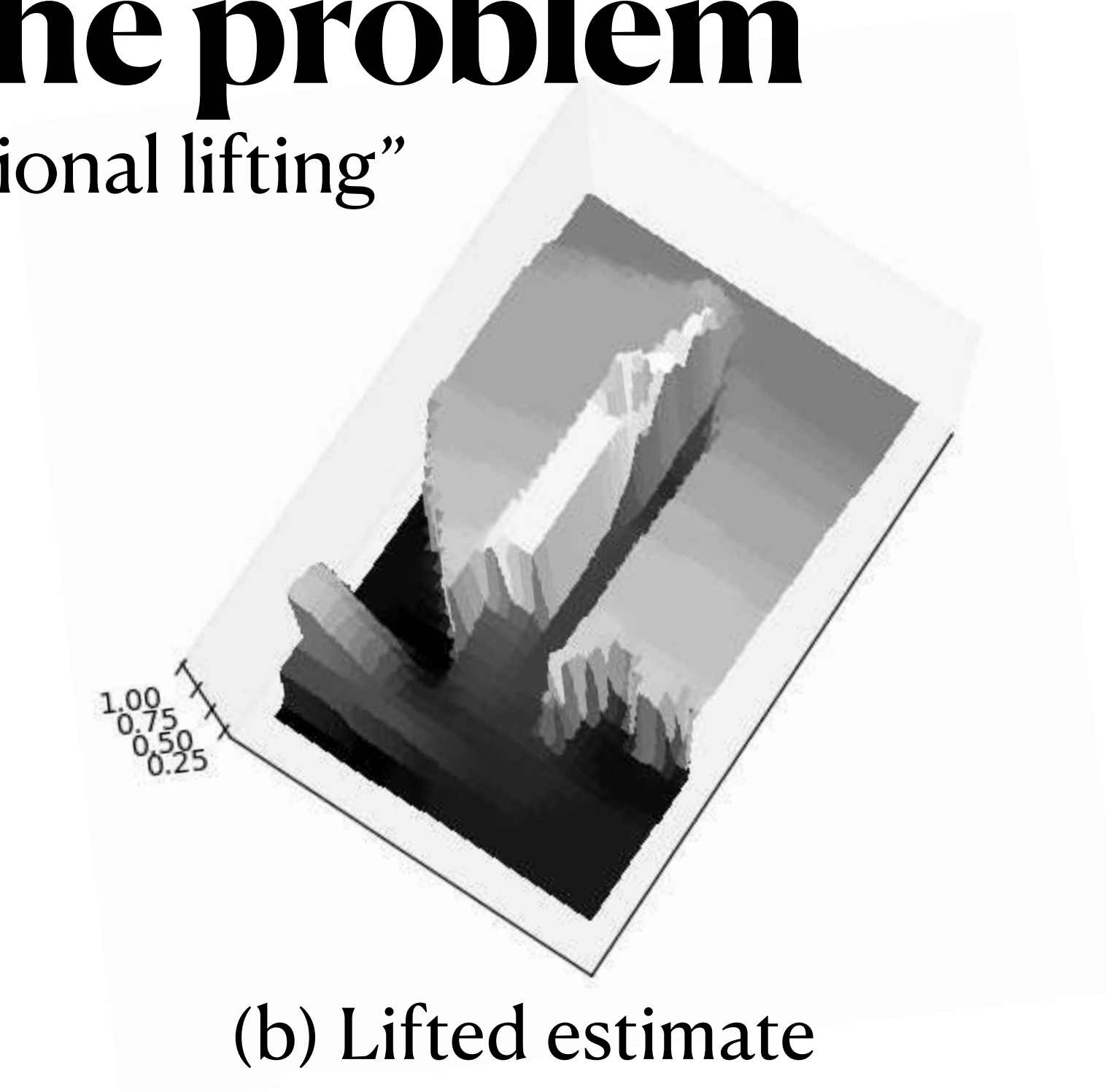


# Convexifying the problem

Example of “functional lifting”



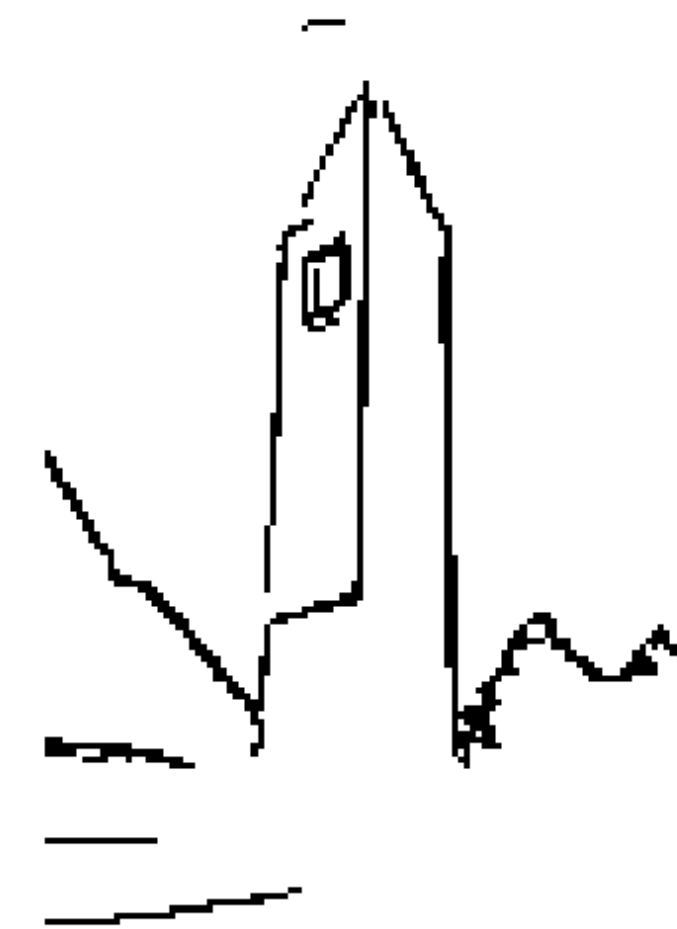
(a) Original image



(b) Lifted estimate



(c) Estimated isosurface



(d) Estimated boundary

# Convexifying the problem

Example of “functional lifting”

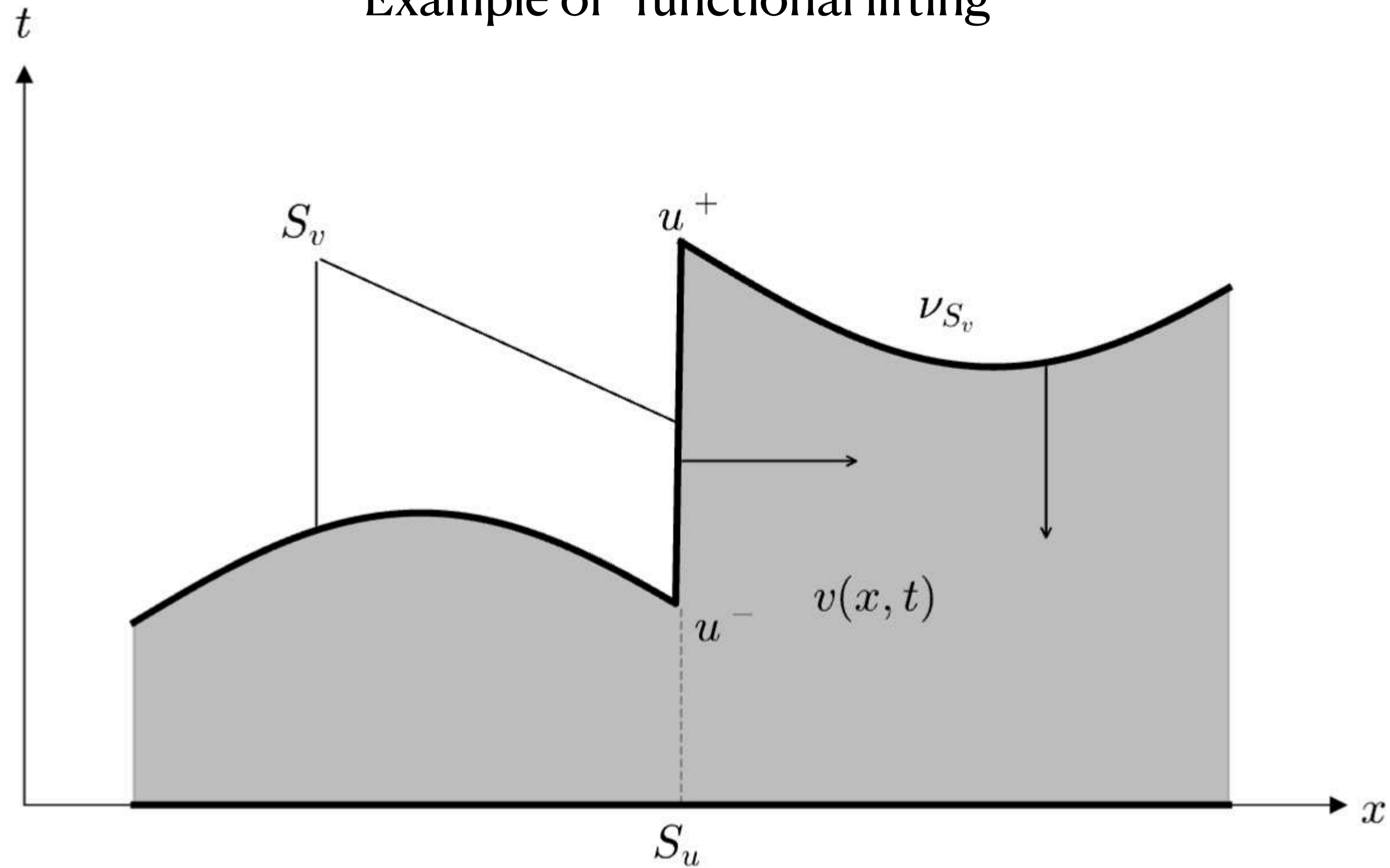


Figure A-1: Convex Relaxation Through Functional Lifting

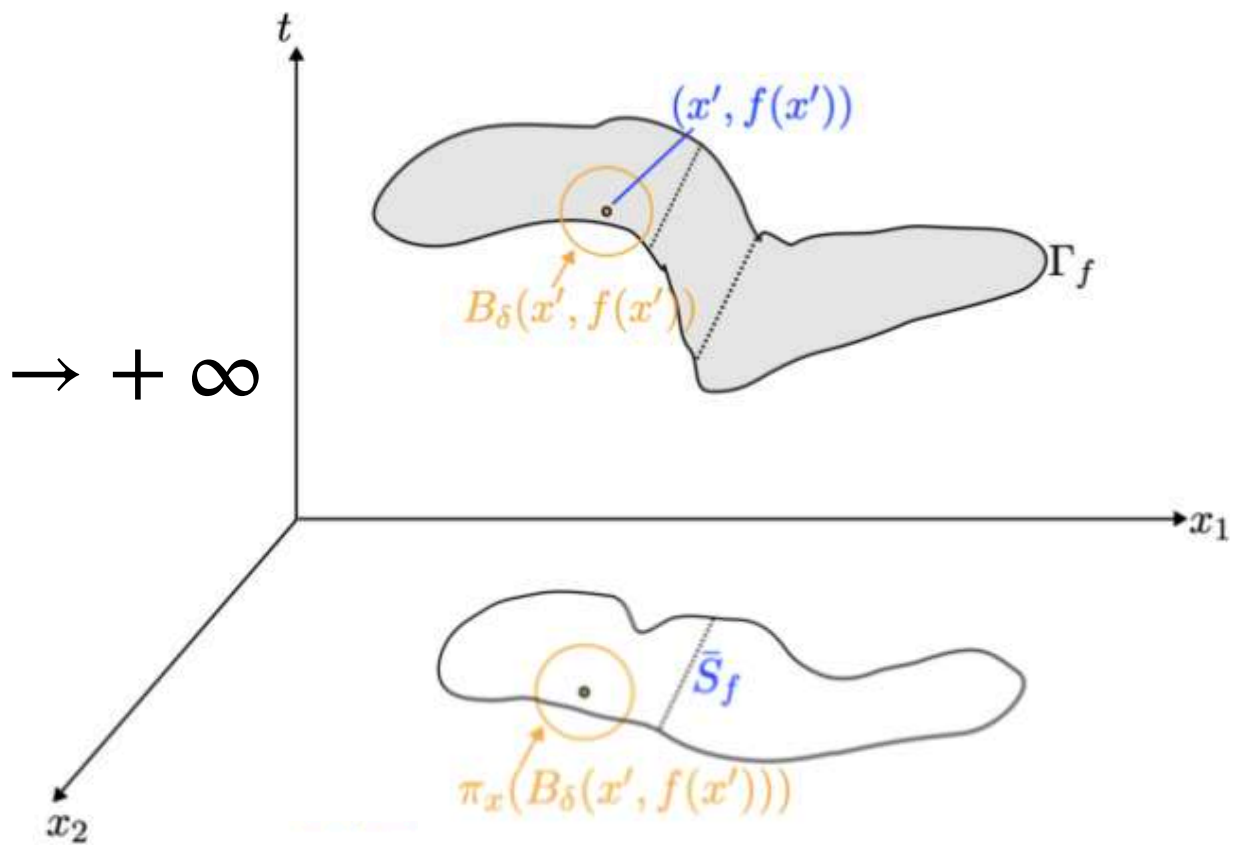
# Identification

We prove that we identify **both the location of the discontinuity as well as the jump sizes in the limit as  $\lambda \rightarrow +\infty$**

**Assumption 2** (i)  $f_X(x) \geq c > 0$  on its support  $\mathcal{X}$ ; (ii)  $f \in SBV(\mathcal{X})$  and bounded almost everywhere; (iii)

$$\int_{\mathcal{X}} |\nabla f|^2 dx + \mathcal{H}^{d-1}(S_f) < +\infty.$$

**Assumption 3** For any  $x \in S_f$  it holds  $\mathcal{H}^{d-1}(S_f \cap B_\rho(x)) > 0$  for all  $\rho > 0$ . Moreover, for any set  $A \subset \mathcal{X}$  with  $\text{dist}(A, S_f) > 0$  there exists a constant  $0 < L < +\infty$  such that  $|f(x) - f(y)| \leq L|x - y|$  for all  $x, y \in A$ .



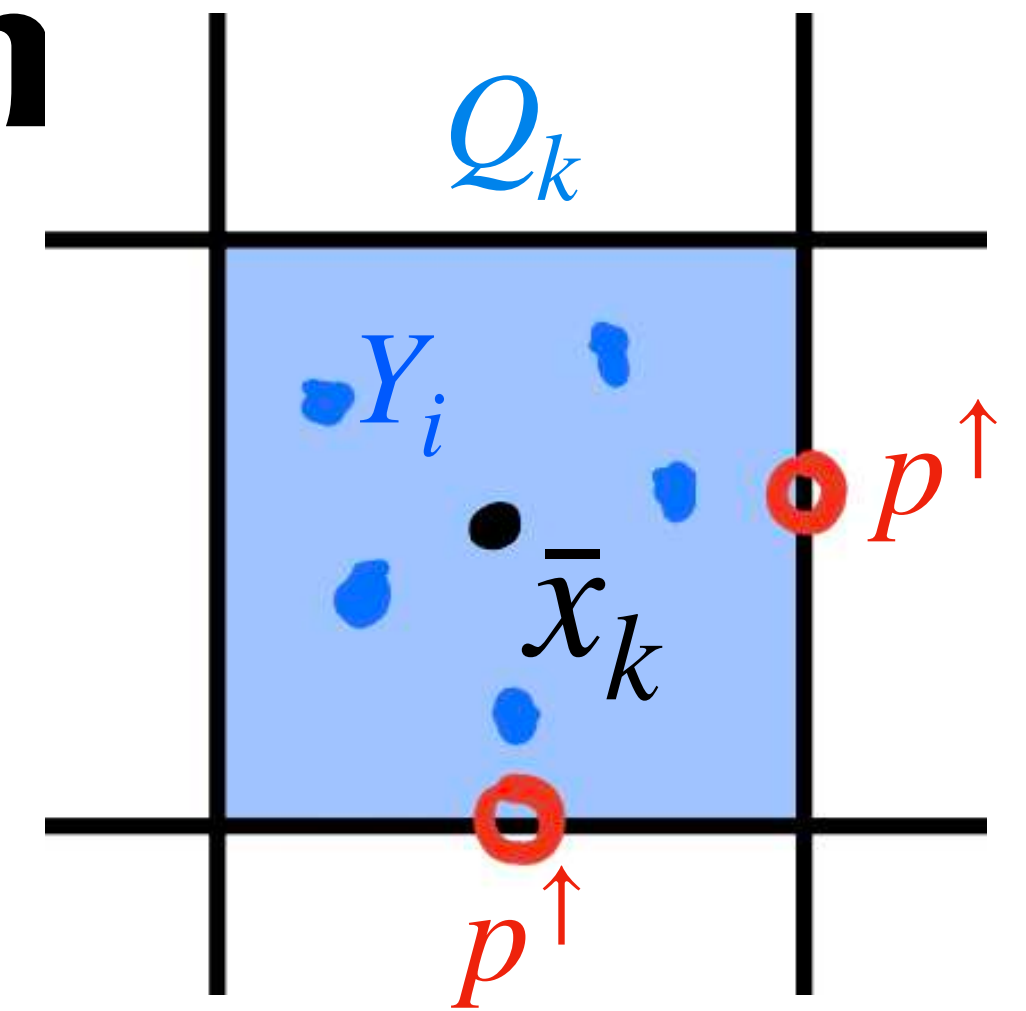
**Theorem** Let Assumptions 2 and 3 hold. Then for fixed  $\nu > 0$  and in the limit as  $\lambda \rightarrow +\infty$  every sequence of solutions  $v^*(\lambda)$  to the optimization problem satisfies  $\lim_{\lambda \rightarrow +\infty} \nabla v^*(\lambda) = 0$   $\mathcal{L}^{d+1}$ -almost everywhere. Moreover, the jump set  $J_{v^*}(\lambda)$  converges in Hausdorff distance to the graph  $\Gamma_f$  of  $f$ , i.e.

$$\lim_{\lambda \rightarrow +\infty} d_H(J_{v^*}, \Gamma_f) = 0.$$

This problem complements existing deep results for the classical MS functional (Morini 2001, Richardson 1992), but is more general, because we get convergence of **the entire graph in Hausdorff distance**. Existing results show identification of the discontinuity set  $S_f$ .

# Empirical implementation

Random data points on grid.



$$\hat{f}_{X, Nn}(\bar{x}_k) = \frac{1}{nh} \sum_i^n K\left(\frac{\bar{x}_k - X_i}{h}\right)$$

$$\hat{f}_{Nn}(\bar{x}_k) = \sum_{i: X_i \in Q_k} w_i Y_i$$

$$\min_{v \in \tilde{C}_N} \max_{p \in \hat{K}_{Nn}} \langle p, D_N v \rangle_N$$

$$\hat{K}_{Nn} = \left\{ p = (p^x, p^t)^T \in Y : p^t(i_1, \dots, i_d, k) \geq \frac{|p^x(i_1, \dots, i_d, k)|^2}{4 \hat{f}_{X, Nn}(i_1, \dots, i_d)} - \lambda \hat{f}_{X, Nn}(i_1, \dots, i_d) \left( \frac{k}{S} - \hat{f}_{Nn}(i_1, \dots, i_d) \right)^2, \left| \frac{1}{N} \sum_{k_1 \leq k \leq k_2} p^x(i_1, \dots, i_d, k) \right| \leq \nu \right\},$$

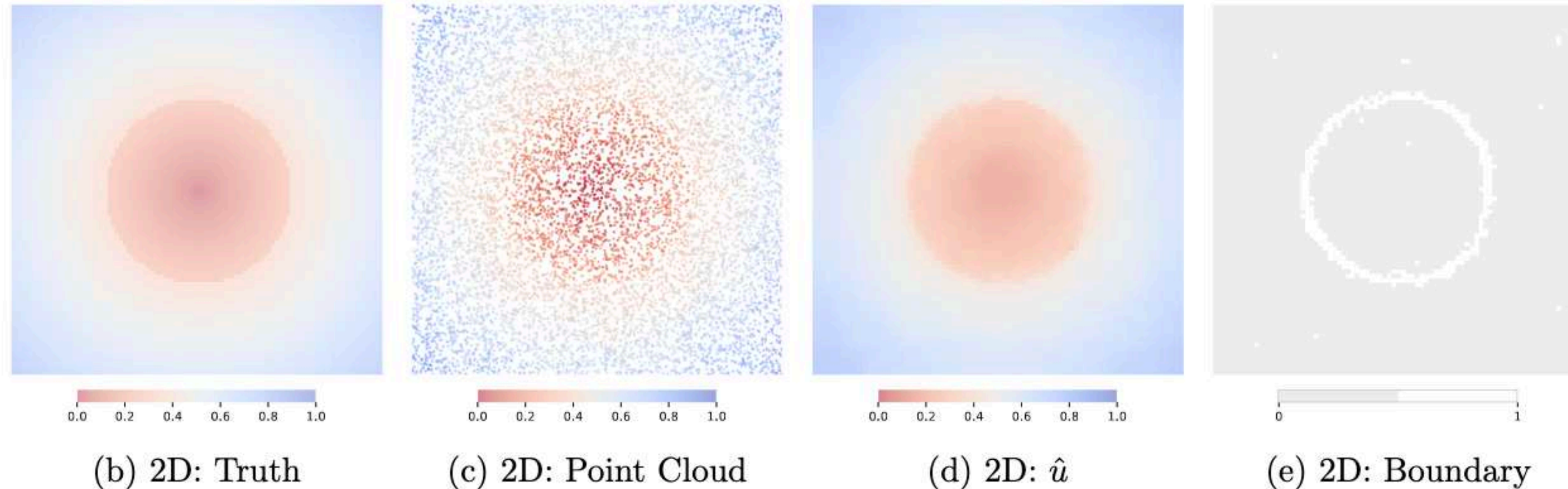
$$\tilde{C}_N = \left\{ u \in X : v(i_1, \dots, i_d, k) \in [0, 1], v(i_1, \dots, i_d, 1) = 1, v(i_1, \dots, i_d, S) = 0 \right\}$$

Solve this problem using a **primal-dual gradient descent-ascent** algorithm (Chambolle and Pock, 2011).

# Obtaining the boundary

Existing methods back out the **discontinuity set** by **thresholding the gradient** of the optimal  $u^*$ :

$$J_u = \left\{ (i, j) : |\nabla u^*(i, j)| \geq \sqrt{\nu} \right\}.$$



**How to pick a good  $\nu$  in practice?** **Hyperparameter selection via a version of Stein's Unbiased Risk Estimate (SURE)**, see also Lucas et. al. (2023) for classical MS.

# Statistical consistency

We prove consistency via  $\Gamma$ -convergence (dal Maso, 2012).

**Assumption 5:** *The density  $f_X$  is bounded away from zero on its compact support  $\mathcal{X}$ . The function  $f(x) \in BV([0,1]^{d+1})$  is bounded.*

**Theorem:** *Let Assumption 1 hold and let  $N(n) \rightarrow 0$  with  $Nn \rightarrow +\infty$  as  $n \rightarrow +\infty$ . Then*

$$\hat{E}_{Nn}(v) = \sup_{p \in \hat{K}_{Nn}} \langle p, D_N v \rangle_N$$

*$\Gamma$ -converges in the weak\*-topology in probability to*

$$E(v) = \begin{cases} \sup_{p \in K} \int_{[0,1]^{d+1}} p \cdot Dv & \text{if } v \in C \\ +\infty & \text{else} \end{cases}.$$

This is the first convergence result for convexified MS and complements recent convergence results in this area:

Chambolle & Pock (2021), Caroccia et. al. (2020), García-Trillos & Slepcev (2016), Chambolle et.al. (2017)

Together with **compactness criterion** (simple) this proves **consistency of the minimizer**.



# Hyperparameter tuning

- **Data-driven** choice for  $\theta = (\lambda, \nu)$ : SURE (Stein, 1981)

- Data-generating process:

$$\tilde{f} = f + \varepsilon, \quad \varepsilon \sim N(0, \sigma^2) \in \mathbb{R}^n$$

- Given an estimator  $\hat{u}_\theta(\tilde{f})$  for  $f$ , the SURE is,

$$\eta(\hat{u}_\theta(\tilde{f})) = \frac{1}{N} \|\tilde{f} - \hat{u}_\theta(\tilde{f})\|^2 - \sigma^2 + 2\sigma^2 \operatorname{div}_f \hat{u}_\theta(\tilde{f}).$$

- Stein's lemma proves that  $\hat{u}_\theta(\tilde{f})$  is an **unbiased estimator of the mean squared error**,

$$MSE(\hat{u}_\theta(f)) := \frac{1}{N} \|\hat{u}_\theta(f) - y\|^2.$$

- In practice, we compute  $\operatorname{div}_f \hat{u}_\theta(\tilde{f})$  using a **Monte-Carlo perturbation approach**

$$\operatorname{div}_y \{ \mathbf{f}_\lambda(\mathbf{y}) \} = \lim_{\varepsilon \rightarrow 0} E_{\mathbf{b}'} \left\{ \mathbf{b}'^T \left( \frac{\mathbf{f}_\lambda(\mathbf{y} + \varepsilon \mathbf{b}') - \mathbf{f}_\lambda(\mathbf{y})}{\varepsilon} \right) \right\},$$

which gives an asymptotically unbiased estimator of the divergence.

- Implemented in parallel in the [Python Ray library](#), currently takes 4-12 hours



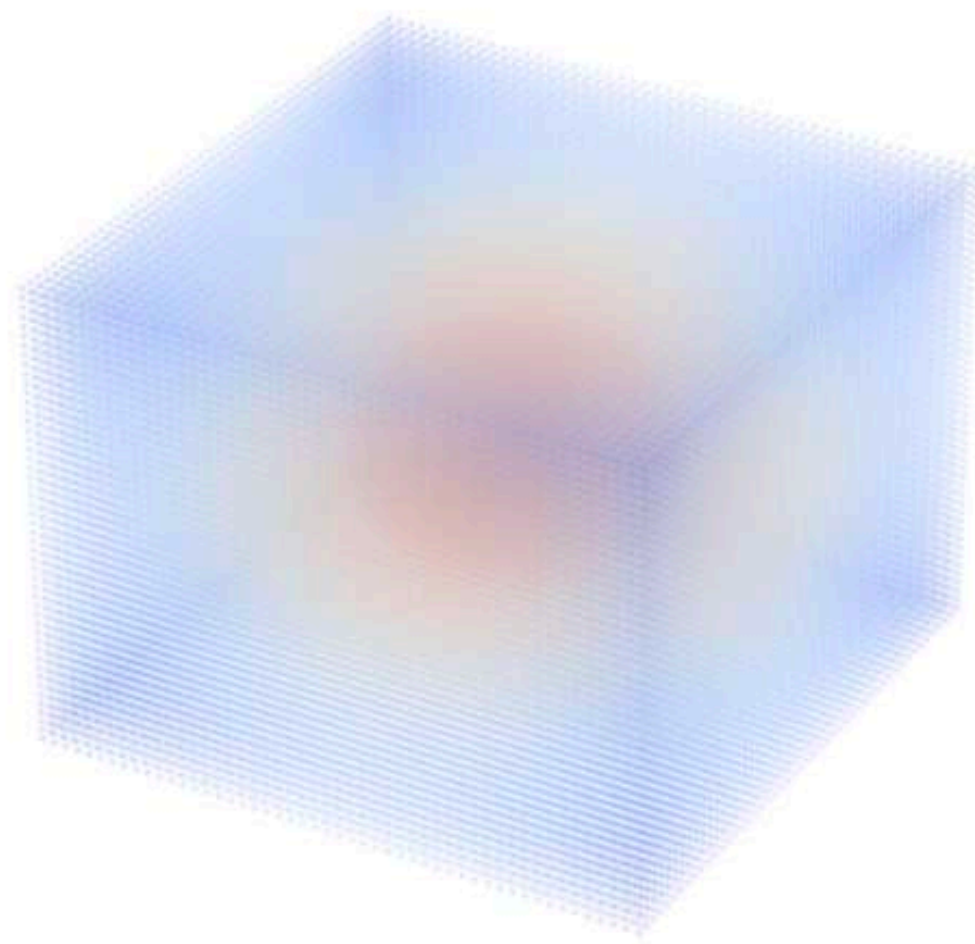
# Practical implementation

## Details

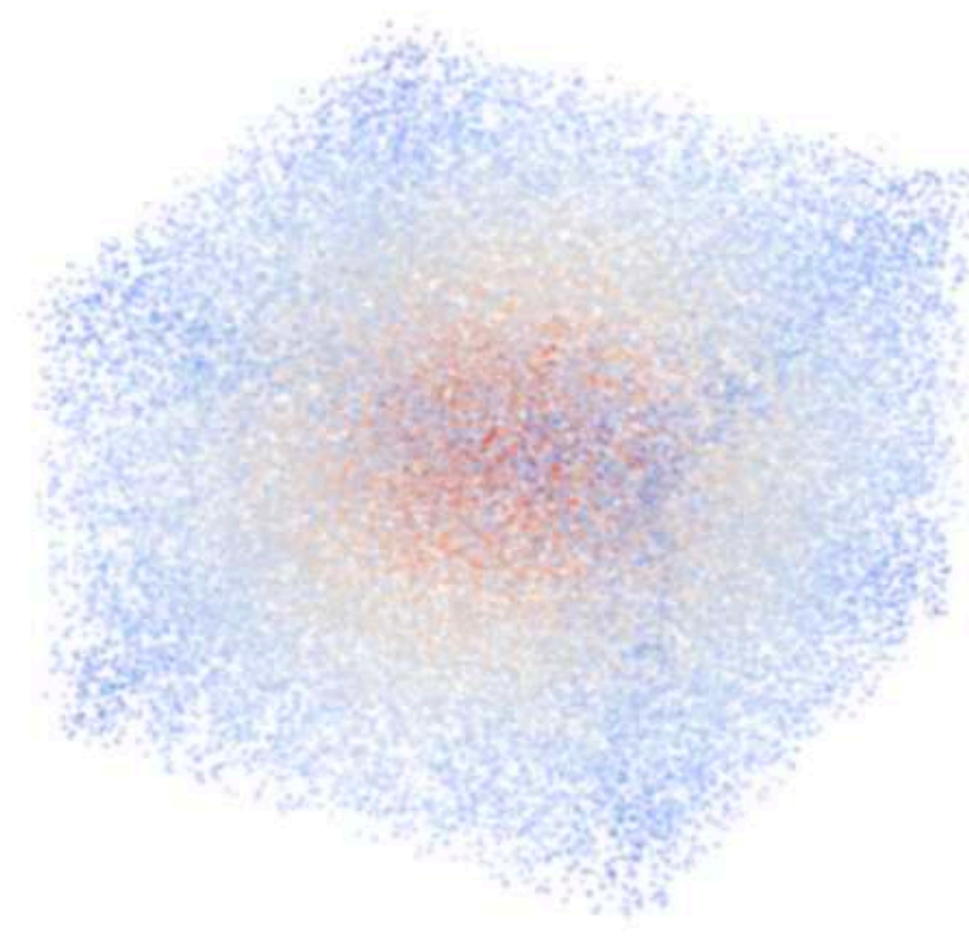


- Implemented in **PyTorch** with support for Nvidia (CUDA), Intel, and Apple Silicon GPU acceleration
  - Extensions to R, STATA in progress
  - Benchmark:
    - Nvidia Tesla A100 Tensor Core GPU
    - $n=90,000$ ;  $N_{grid} = 12,750$  (25%);  $S=32$
    - Execution time: **69.37 seconds**
    - Can be improved by using approximations of the cost function (“sublabel”) (Mollenhoff and Cremers, 2017)

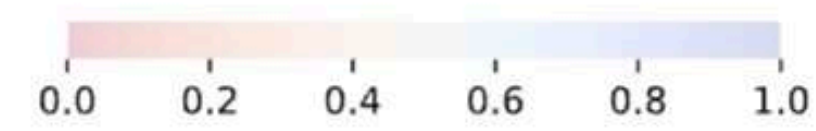
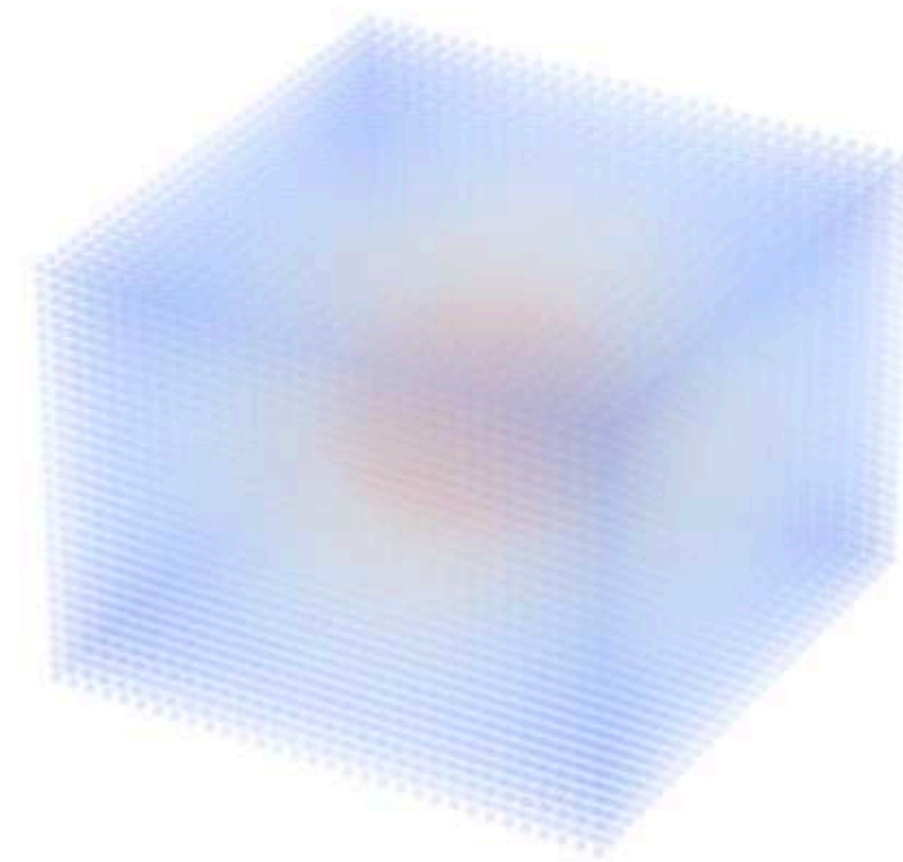
# Simulations



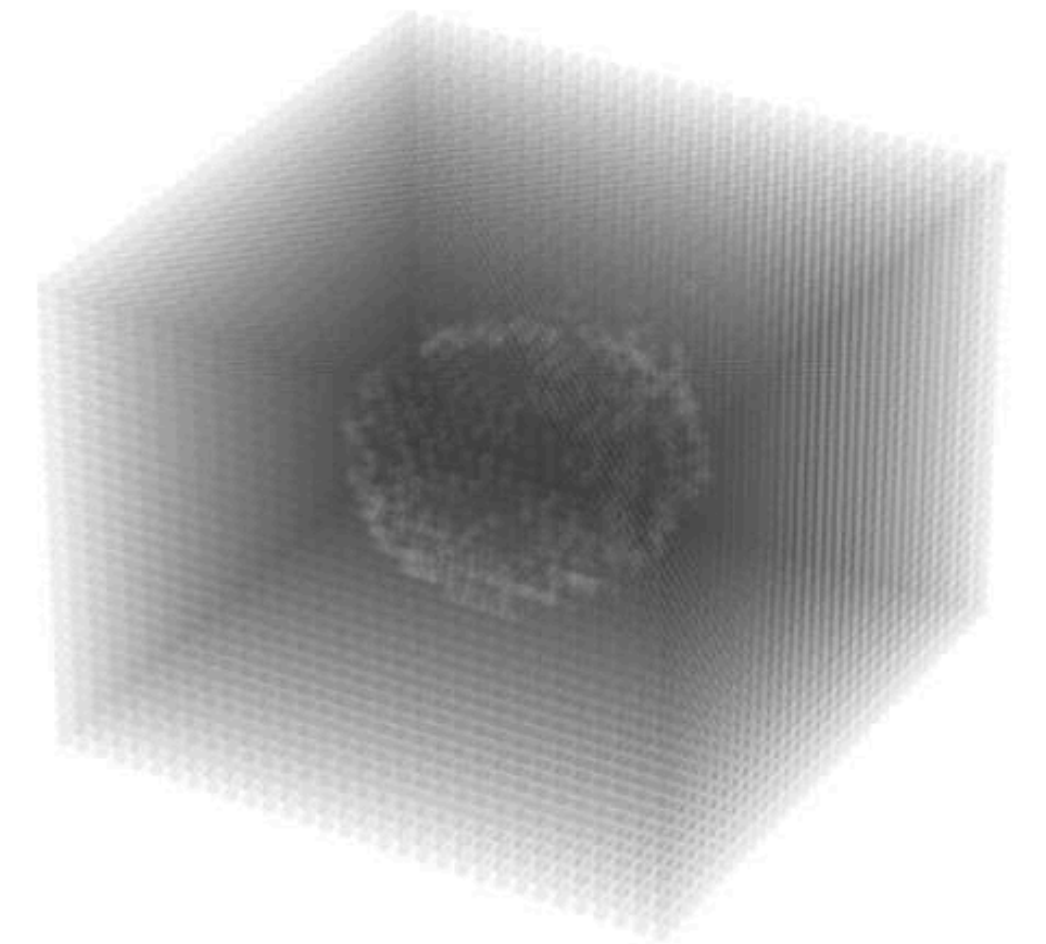
(f) 3D: Truth



(g) 3D: Point Cloud



(h) 3D:  $\hat{u}$



(i) 3D: Boundary

Table 1: Monte Carlo Simulations

(a) 1D

n	MSE	MSE $\tau_{\text{FD}}$	Bias $\tau_{\text{FD}}$	FNR	FPR
500	0.0789	0.0358	-0.084	-0.0437	0.1933
1000	0.0461	0.0305	-0.0659	0	0.1099
5000	0.0012	0.0099	-0.053	0	0.018

SURE:  $\lambda = 98.6712$ ,  $\nu = 0.0001$ 

(b) 2D

d = 0.25

n	$\alpha$	$\hat{\alpha}$	MSE	MSE $\tau_{\text{FD}}$	Bias $\tau_{\text{FD}}$	FNR	FPR
1000	0.0375	0.0698	0.0022	0.0027	0.0323	0.0098	0.6757
5000	0.0375	0.0351	0.001	0.0002	-0.0024	0.0735	0.2319
10000	0.0375	0.0297	0.0009	0.0001	-0.0078	0.269	0.0391

SURE:  $\lambda = 65.6470$ ,  $\nu = 0.0010$ 

d = 0.50

n	$\alpha$	$\hat{\alpha}$	MSE	MSE $\tau_{\text{FD}}$	Bias $\tau_{\text{FD}}$	FNR	FPR
1000	0.075	0.0859	0.0025	0.0021	0.0108	0.0159	0.561
5000	0.075	0.056	0.0011	0.001	-0.0191	0.0848	0.0837
10000	0.075	0.0545	0.001	0.0007	-0.0206	0.1476	0.0072

SURE:  $\lambda = 107.6274$ ,  $\nu = 0.0019$ 

d = 0.75

n	$\alpha$	$\hat{\alpha}$	MSE	MSE $\tau_{\text{FD}}$	Bias $\tau_{\text{FD}}$	FNR	FPR
1000	0.1126	0.0953	0.003	0.0027	-0.0173	0.0093	0.5902
5000	0.1126	0.0732	0.0016	0.0036	-0.0394	0.0588	0.1676
10000	0.1126	0.078	0.0012	0.0027	-0.0346	0.0901	0.0181

SURE:  $\lambda = 209.4585$ ,  $\nu = 0.0020$

# Application: Internet Shutdowns



- Various district governments of Rajasthan state, India [shut down mobile internet](#) on September 26, 2021 from 6am to 6pm to prevent cheating on the Rajasthan Eligibility Exam for Teachers (REET).
- Mobile network coverage in India is much better than WiFi/wired: [major disruption of economic activity](#)
  - WiFi 0.08% of wireless connectivity, wired connection only 3.74% of total internet subscriptions
  - Estimated 80,000 shops closed in Jaipur alone (The Economist, 2021)
  - Mobile payments ubiquitous (UPI), large digital economy, disruption of business operations, rural businesses no wired connection
- Estimate impact on mobile device signal using mobile device data from [Veraset](#), a mobility data provider
  - [126 million pings](#) in area on day of shutdown
  - [3.8 million](#) unique devices (10% of mobile population)
- Perfect setting for our estimator:
  - **Unknown discontinuity**: diffuse area, not all districts that shut down issued official mandate, disconnected at point of contact
  - **Multivariate assignment**: latitude-longitude
- Effect on connectivity can serve as first-stage for downstream outcomes, we focus on economic activity

# Application: Internet Shutdowns

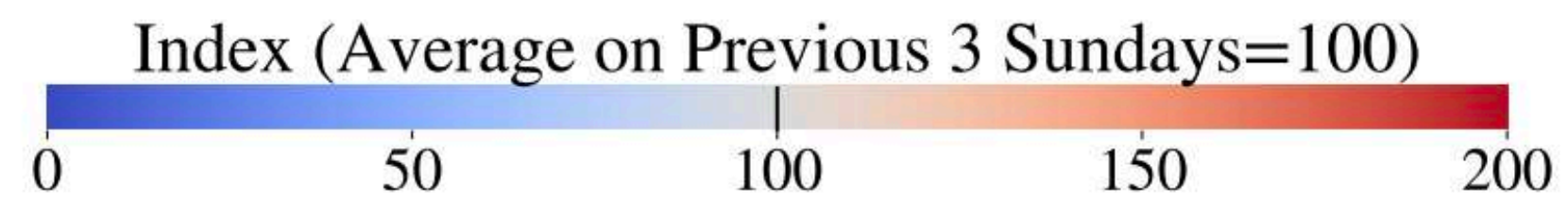
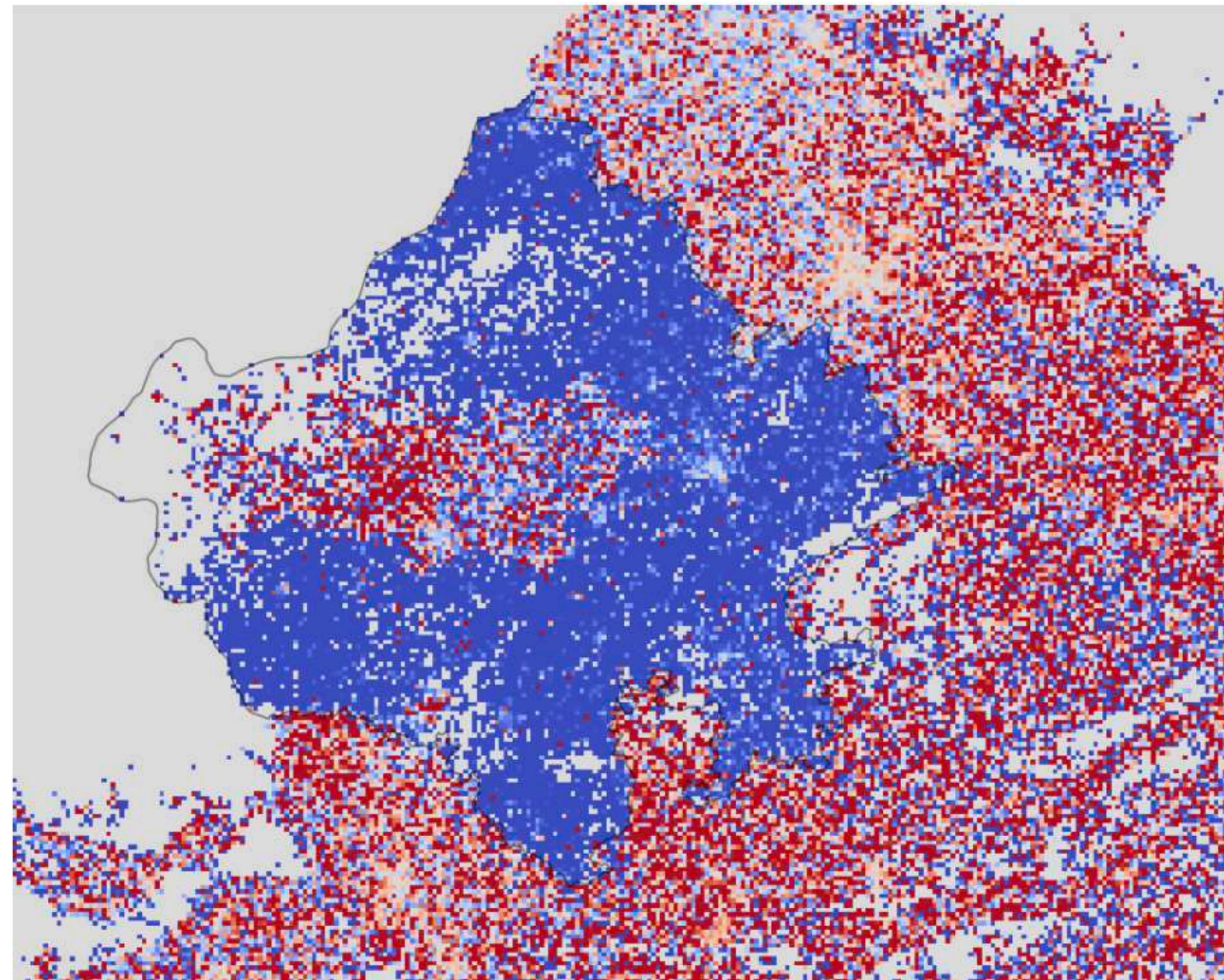
- Main outcomes:

$$\overline{Pings}_i := \frac{Pings_{it_0}}{\frac{1}{3} \sum_{t=t_0-3}^{t_0-1} Pings_{it}},$$

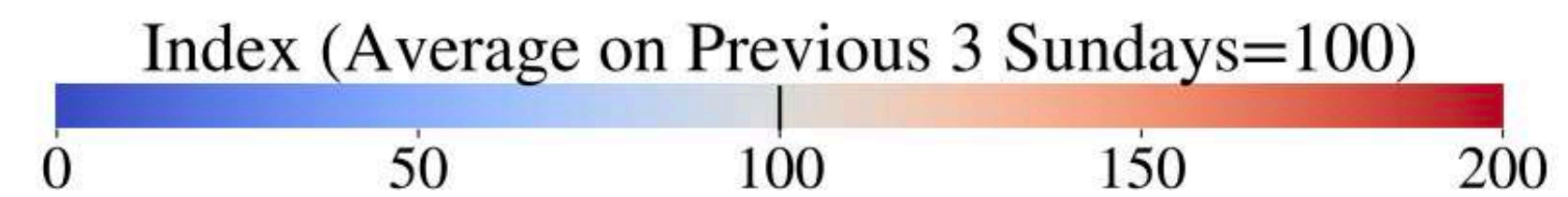
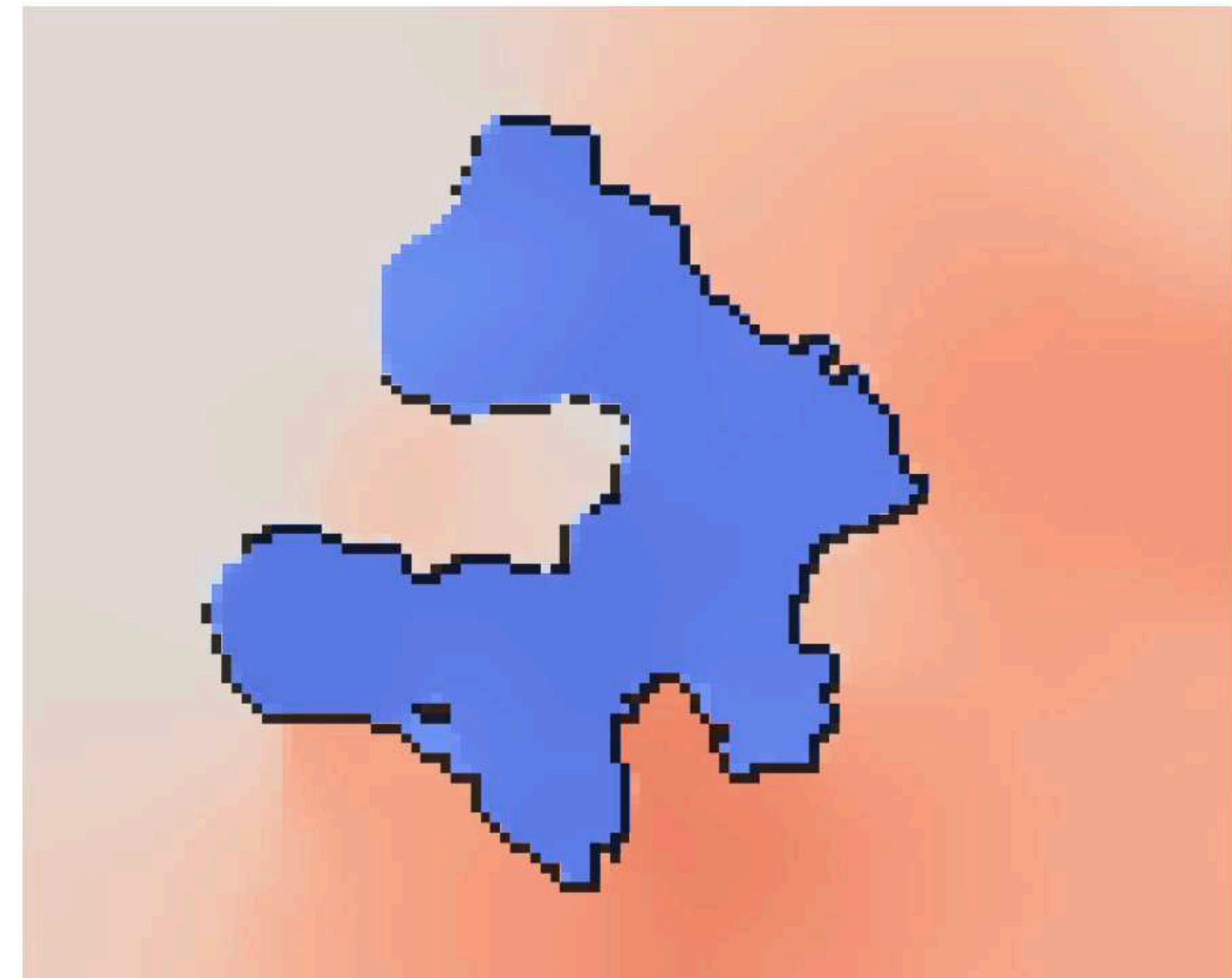
- Index of **total pings inside 5x5 km grid** cells, relative to prior month average in same time window
- Measure economic impact: **share of pings inside 40x40 km grid cells that fall in “economic areas”**
  - “**Economic areas**”: commercial or public OSM POI + SafeGraph shops — 108K polygons
- Idea: use remaining “**cached**” pings from satellite that get uploaded once internet connection is restored
- Assumption: disruption of numerator (economic pings) and denominator (total pings) is same
  - 1) economic activity of **mobile users with continuous background** location is representative: ~67% of Android users have it
  - 2) set of **apps that cache background location** is not skewed: by construction (continuous) + sourced from 1,000+ mobile apps (SDK)

# Application: Internet Shutdowns

## Mobile Signal



(a) Mobile: Raw Data

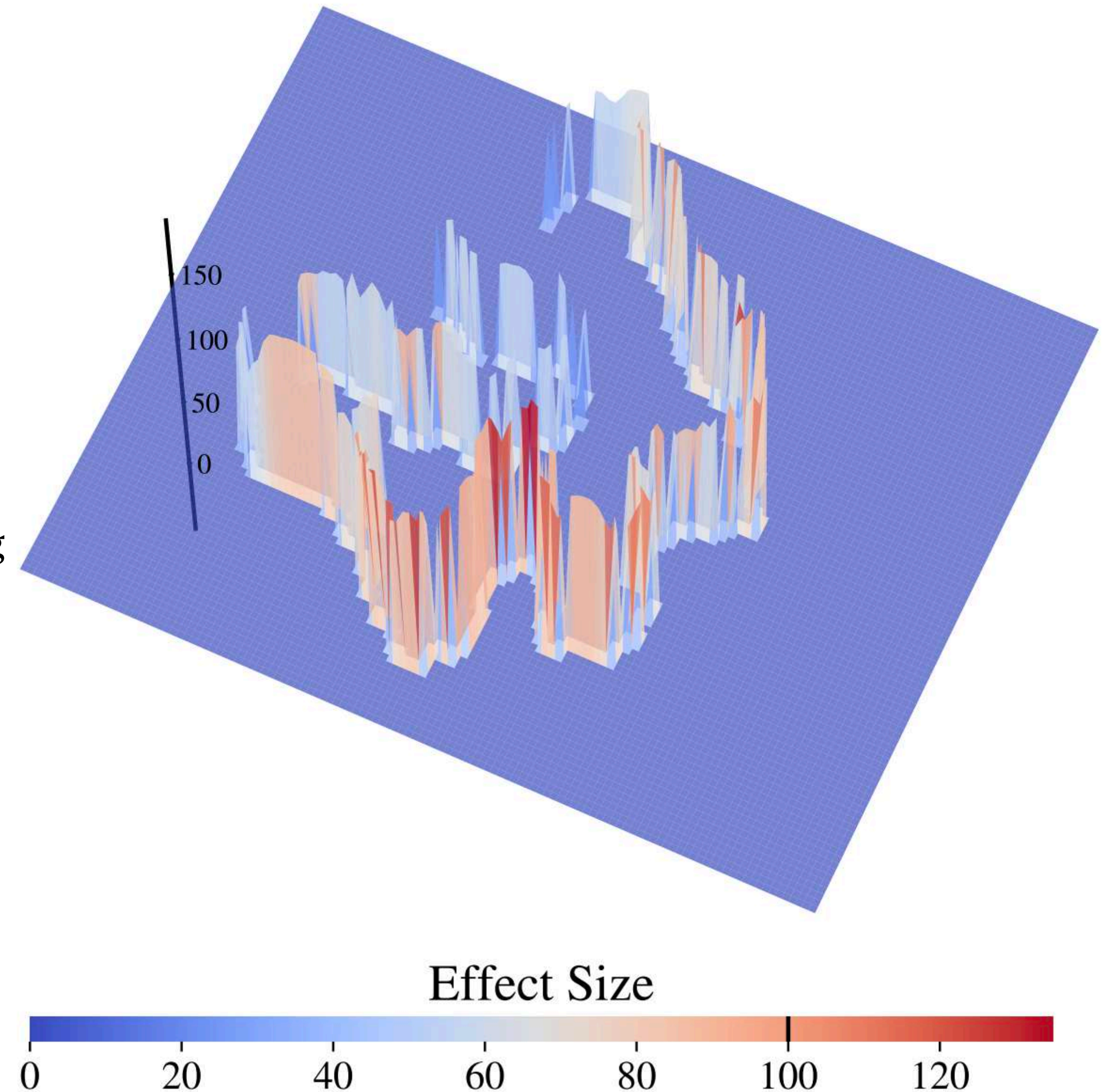


(b) Mobile:  $\hat{u}$  &  $S_u$

# Application: Internet Shutdowns

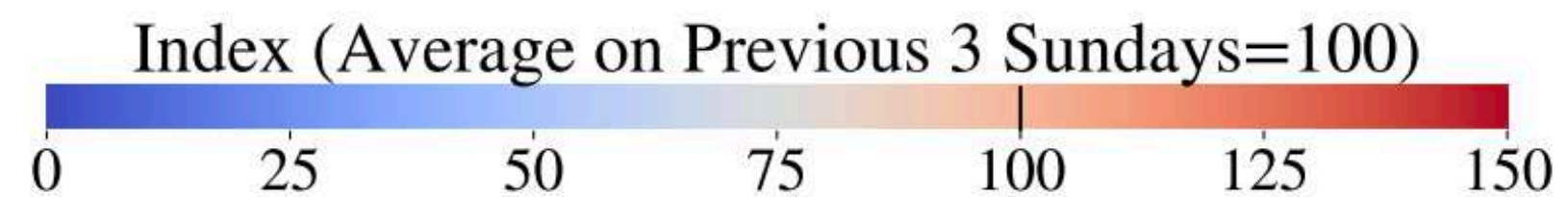
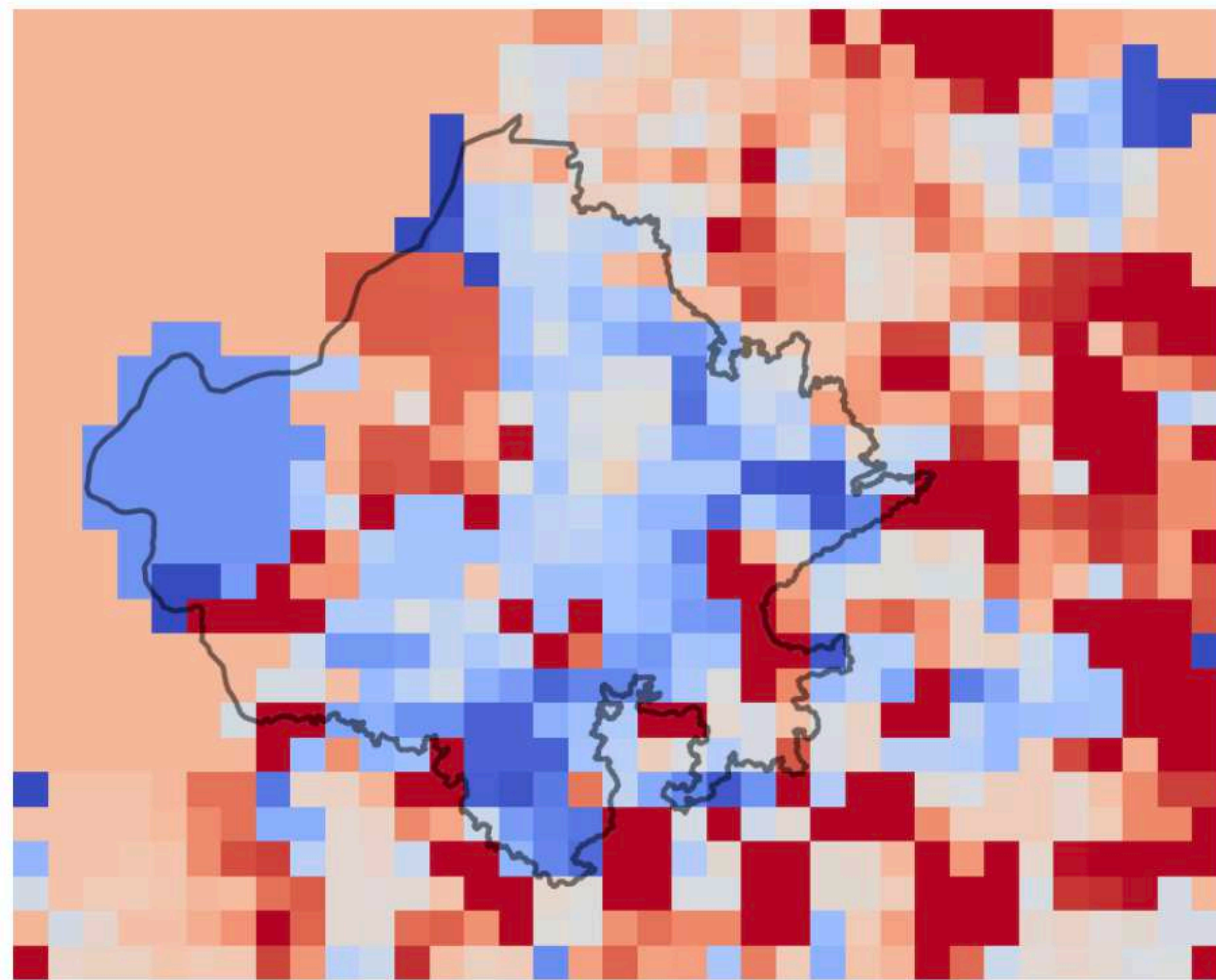
## Mobile signal: treatment Effect Curve

- Average drop of 100% relative to month average
- Increase in activity in connected areas: COVID rebound
- Overall: shutdown highly effective at disrupting mobile signal
- 25% of signal inside shutdown area remains due to satellite caching

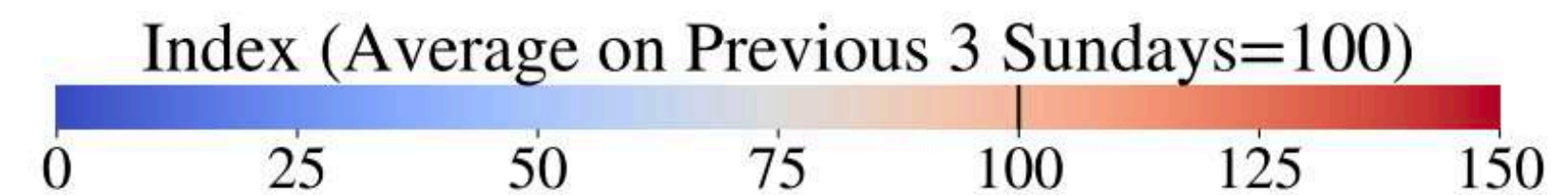




# Application: Internet Shutdowns



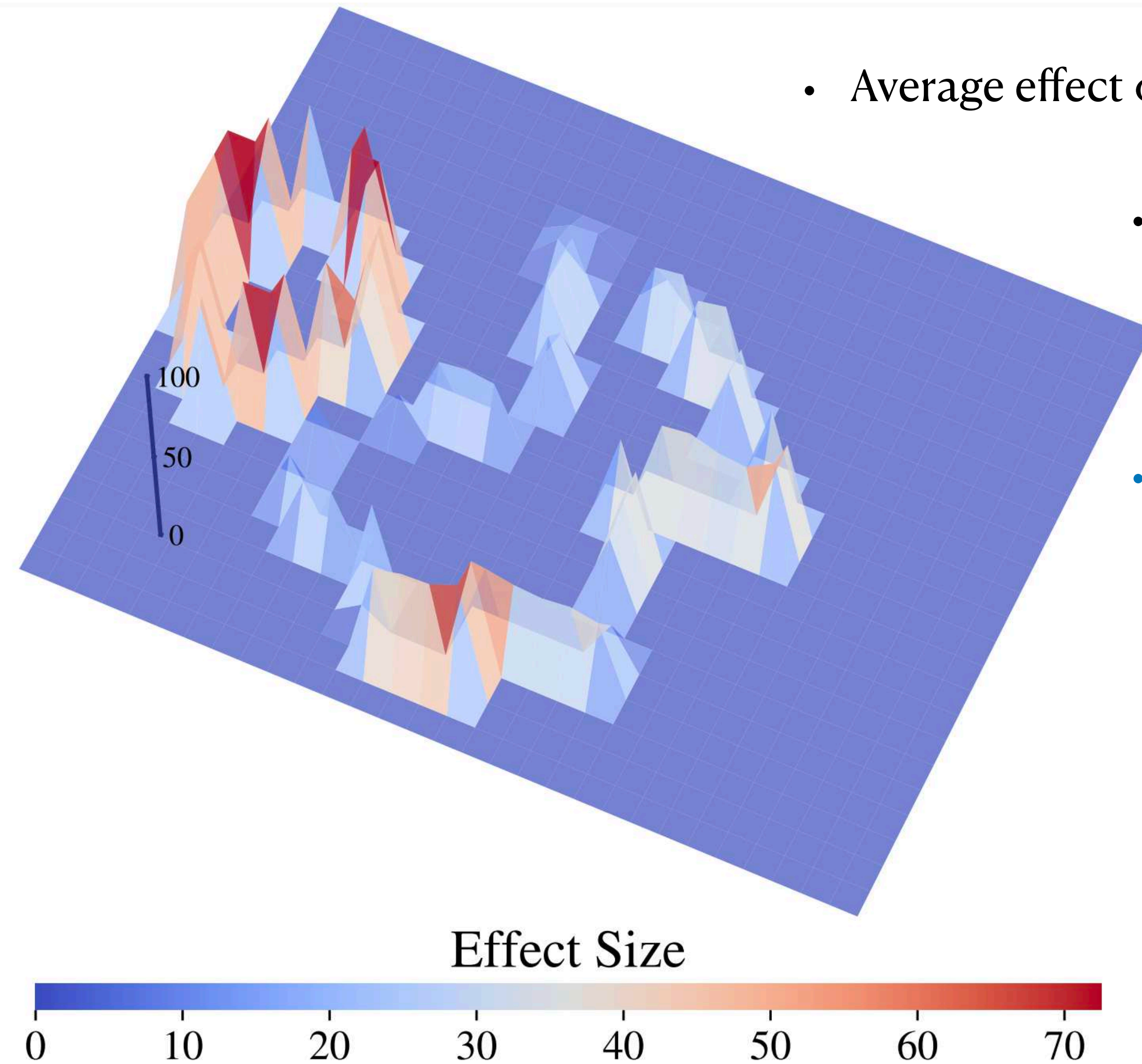
(a) Economic: Raw Data



(b) Economic:  $\hat{u}$  &  $S_u$

# Application: Internet Shutdowns

## Economic Activity: Treatment Effect Curve



(c) Economic:  $\tau_{FD}(x)$

- Average effect of **35% of monthly average** (0-5% baseline increase)

- Correlation of at least 0.7 between mobility data and economic activity (Dong et. Al. 2017):

**25%+ drop in economic activity**

- **50% higher than highest prevalent estimate!**
  - Based on old, single estimate of “digital multiplier”
  - Likely increased drastically since then
  - Digital disruptions can affect non-digitized sections of economy as well through its “enabling role” (Cybersecurity and Infrastructure Security Agency, n.d.)

# Conclusion

- **Free discontinuity problem** is a penalized regression estimation problem **with unknown discontinuity in multiple dimensions**
- Connection to **Mumford-Shah functional, convexified via standard lifting approach (calibrations)**
- First mathematical and statistical **identification and consistency** results
- **Hyperparameter choice** via SURE
- Uncertainty quantification via **conformal inference on grid**
- **Application to economic effects of internet shutdowns** finds much stronger **short-term** effects than existing research
- Lots of applications in sciences (several applied papers in progress...)

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# Appendix

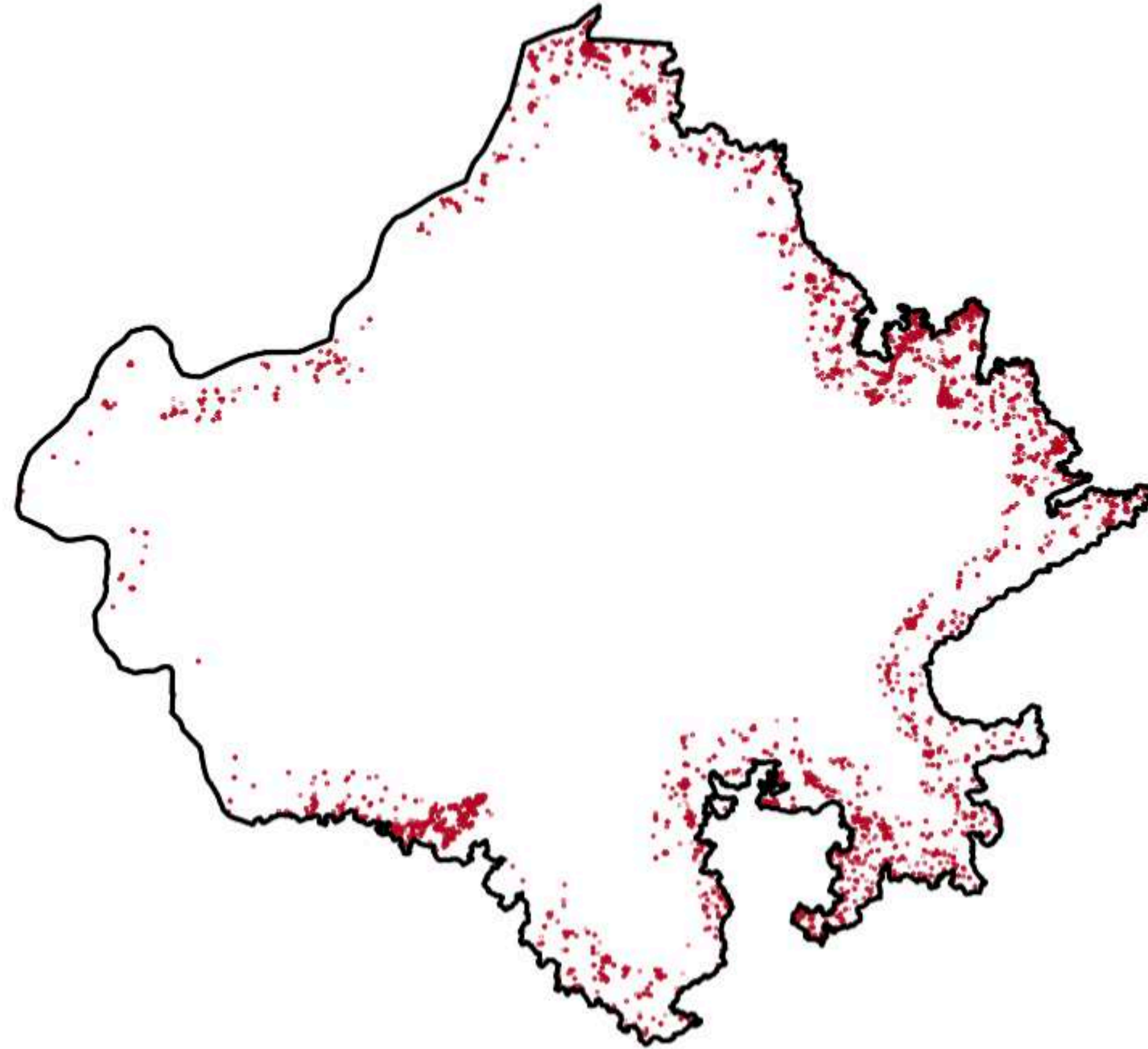


Figure A-1: Catchment Area for Estimating Degree of Selection

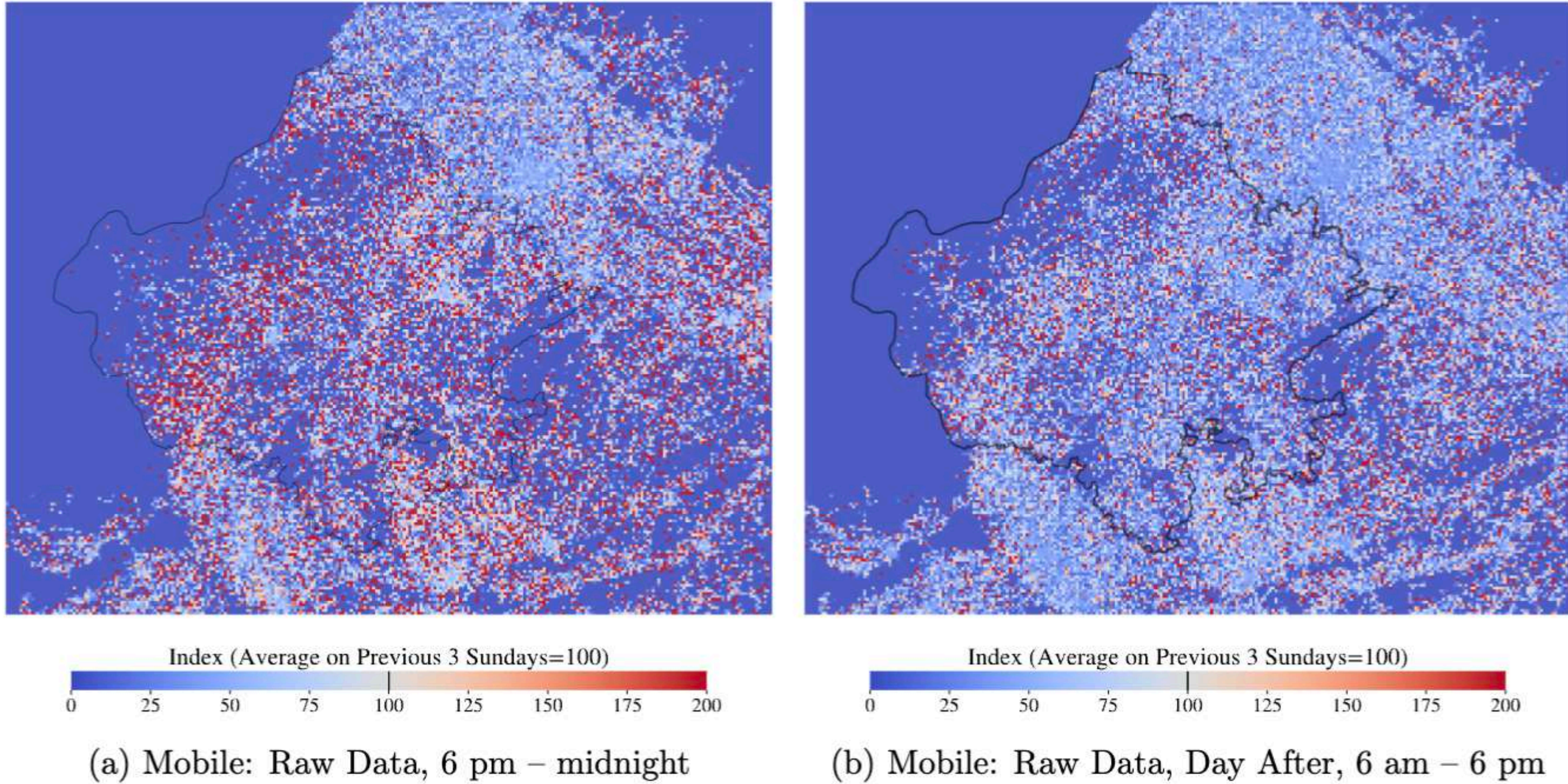
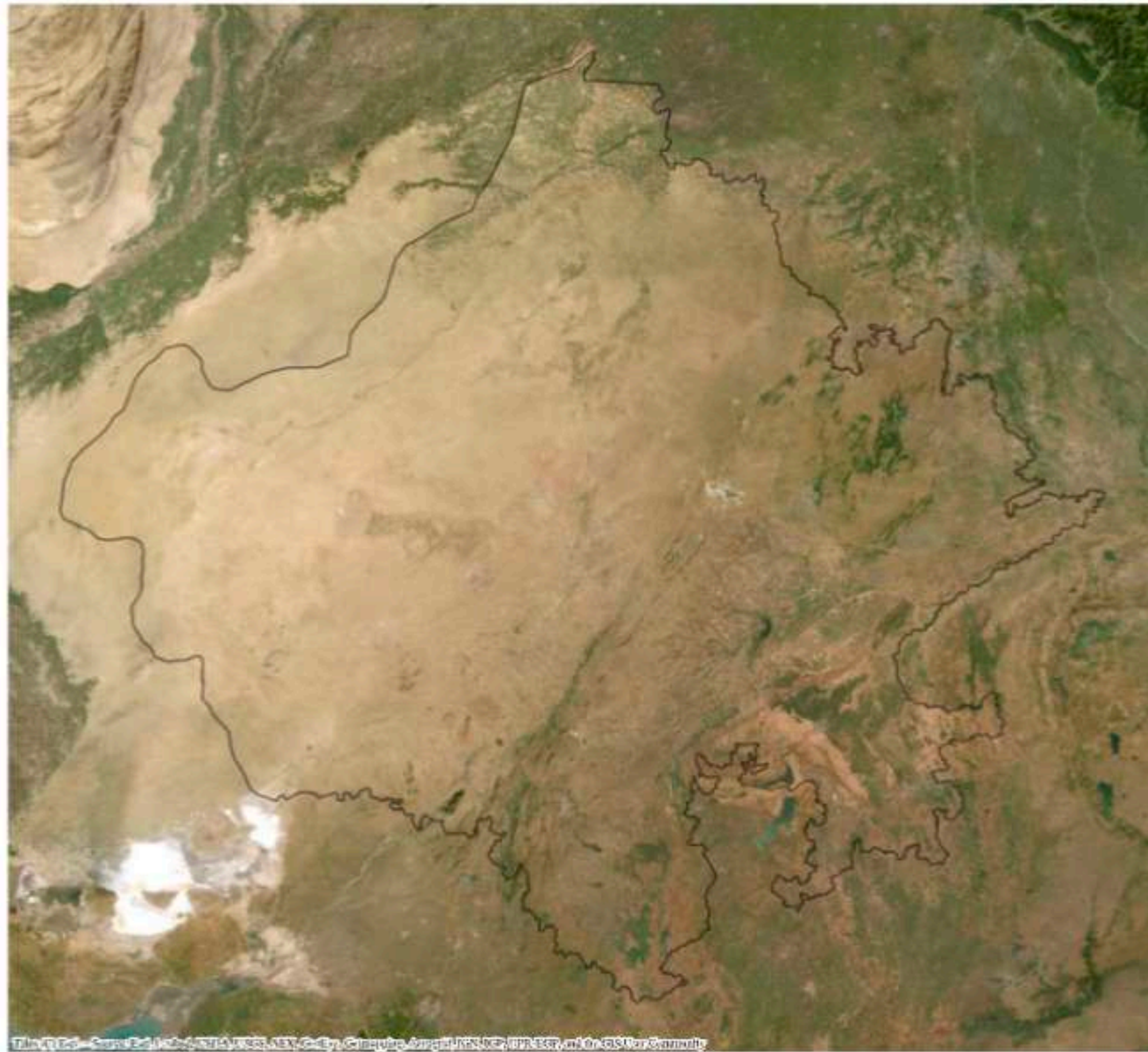
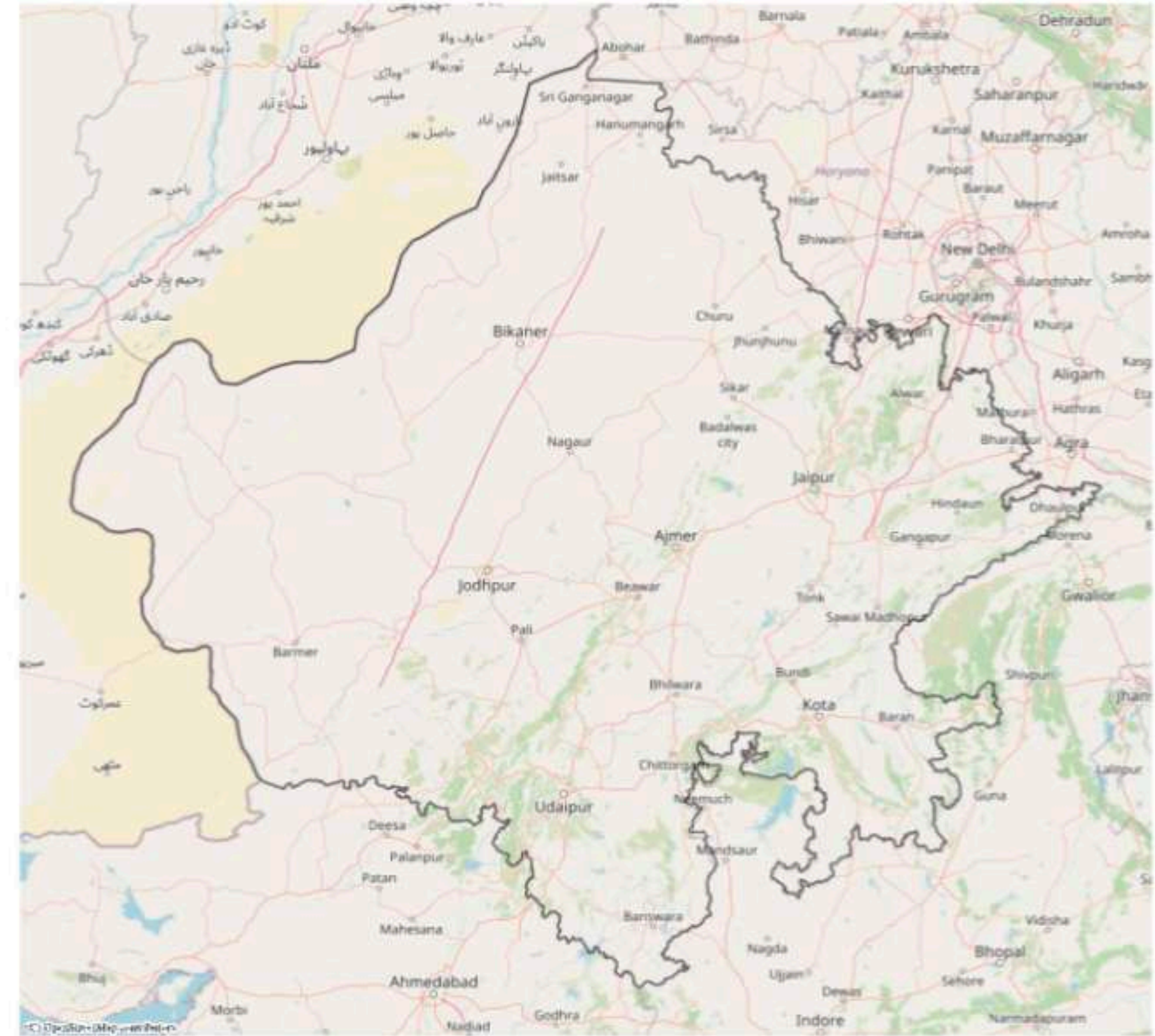


Figure A-3: Post-Shutdown Activity

*Note:* Plot shows the raw mobile device data on a 5x5km grid with the fill color of each cell indicating the value of  $\overline{Pings}$ , for the hours between 6 pm and midnight on the day of the shutdown in (a) and for the time spanning the shutdown window the day after the shutdown in (b). The outline of Rajasthan state is indicated by black lines.



(a) Esri Satellite Imagery



(b) OpenStreetMap

Figure A-4: Rajasthan: Terrain View

*Note:* **A-4a** shows the satellite view of Rajasthan, obtained from Esri; **A-4b** shows the street map of Rajasthan obtained from OpenStreetMap. The outline of Rajasthan is depicted in black.